Ameliorating Systematic Uncertainties in the Angular Clustering of Galaxies: A Study using SDSS-III

Karen Masters
Haverford College, klmasters@haverford.edu
Ashley J. Ross
Shirley Ho
Antonio J. Cuesta

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Ashley J. Ross,1⋆ Shirley Ho,2 Antonio J. Cuesta,3 Rita Tojeiro,1 Will J. Percival,1 David Wake,3 Karen L. Masters,1,4 Robert C. Nichol,1,4 Adam D. Myers,5 Fernando de Simoni,6,7 Hee Jong Seo,8 Carlos Hernández-Monteagudo,9,10 Robert Crittenden,1 Michael Blanton,11 J. Brinkmann,12 Luiz A. N. da Costa,6,7 Hong Guo,13 Eyal Kazin,11 Marcio A. G. Maia,6,7 Claudia Maraston,1 Nikhil Padmanabhan,3 Francisco Prada,14 Beatriz Ramos,6,7 Ariel Sanchez,15 Edward F. Schlafly,16 David J. Schlegel,2 Donald P. Schneider,17 Ramin Skibba,18 Daniel Thomas,1,4 Benjamin A. Weaver,11 Martin White2,19,20 and Idit Zehavi13

1Institute of Cosmology & Gravitation, Dennis Sciama Building, University of Portsmouth, Portsmouth PO1 3FX
2Lawrence Berkeley National Laboratory, 1 Cyclotron Road, Berkeley, CA 94720, USA
3Yale Center for Astronomy and Astrophysics, Yale University, New Haven, CT 06511, USA
4SEPnet, South East Physics Network (www.sepnet.ac.uk)
5Department of Physics and Astronomy, University of Wyoming, Laramie, WY 82071, USA
6Observatório Nacional, Rua Gal. José Cristino 77, Rio de Janeiro, RJ 20921-400, Brazil
7Laboratório Interinstitucional de e-Astronomia - LineA, Rua Gal. José Cristino 77, Rio de Janeiro, RJ 20921-400, Brazil
8Berkeley Center for Cosmological Physics, LBL and Department of Physics, University of California, Berkeley, CA 94720, USA
9Max-Planck-Institut für Astrophysik (MPA), Karl Schwarzschild Strasse 1, Garching bei München D-85741, Germany
10Centro de Estudios de Física del Cosmos de Aragón (CEFCA), Plaza San Juan, 1, Planta 2, E-44001 Teruel, Spain
11Center for Cosmology and Particle Physics, New York University, New York, NY 10003, USA
12Apache Point Observatory, 2001 Apache Point Road, Sunspot, NM 88349, USA
13Department of Astronomy, Case Western Reserve University, Cleveland, OH 44106, USA
14Instituto de Astrofísica de Andalucía (CSIC), Granada, Spain
15Max-Planck-Institut für extraterrestrische Physik, Giessenbachstr. 1, 85748 Garching, Germany
16Department of Physics, Harvard University, 17 Oxford Street, Cambridge, MA 02138, USA
17Department of Astronomy & Astrophysics, The Pennsylvania State University, 525 Davey Lab, University Park, PA 16802, USA
18Steward Observatory, University of Arizona, 933 North Cherry Avenue, Tucson, AZ 85721, USA
19Department of Physics, University of California, 366 LeConte Hall, Berkeley, CA 94720, USA
20Department of Astronomy, 601 Campbell Hall, University of California at Berkeley, Berkeley, CA 94720, USA

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ABSTRACT

We investigate the effects of potential sources of systematic error on the angular and photometric redshift, $z_{\text{phot}}$, distributions of a sample of redshift $0.4 < z < 0.7$ massive galaxies whose selection matches that of the Baryon Oscillation Spectroscopic Survey (BOSS) constant-mass sample. Utilizing over 112 778 BOSS spectra as a training sample, we produce a photometric redshift catalogue for the galaxies in the Sloan Digital Sky Survey eight data release imaging area that, after masking, covers nearly one quarter of the sky ($9913$ deg$^2$). We investigate fluctuations in the number density of objects in this sample as a function of Galactic extinction, seeing, stellar density, sky background, airmass, photometric offset and North/South Galactic hemisphere. We find that the presence of stars of comparable magnitudes to our galaxies

⋆E-mail: Ashley.Ross@port.ac.uk
1 INTRODUCTION

Wide-field, multiband imaging surveys provide photometric redshift estimates for many millions of galaxies. Photometric redshifts, \( z_{\text{phot}} \), are easier to obtain than spectroscopic ones, \( z_{\text{spec}} \), but the gain in numbers of objects is countered by redshift uncertainties, \( \sigma_z \), that are rarely better than \( \sigma_z = 0.03(1 + z) \). Such photometric redshift surveys may be referred to as having ‘two + one’ dimensions – nearly all of the radial clustering information is lost, but the redshift errors are small enough to allow two-dimensional clustering measurements in redshift shells of width similar to \( \sigma_z \). This strategy has been utilized to explore the formation and evolution of galaxies (see e.g. Blake, Collister & Lahav 2008; McCracken et al. 2008; Ross & Brunner 2009; Ross, Percival & Brunner 2010; Ross, Tojeiro & Percival 2011a; Wake et al. 2011) and quasars (e.g. Myers et al. 2006), and also to measure cosmological parameters (see e.g. Blake et al. 2007; Padmanabhan et al. 2007; Ross, Brunner & Myers 2008; Thomas, Abdalla & Lahav 2010, 2011a; Crocce et al. 2011b). Such studies are gaining in importance, as future surveys such as The Dark Energy Survey\(^1\) (DES), the Large Synoptic Survey Telescope\(^2\) (LSST) and the Panoramic Survey Telescope & Rapid Response System\(^3\) (Pan-STARRS) will rely primarily on photometric redshifts.

At the largest scales, the accuracy of clustering measurements is not critically dependent on the uncertainty of each \( z_{\text{phot}} \). However, contaminants or incorrect calibrations do matter at these scales – the predicted clustering amplitudes are negligible; systematic errors can cause small fluctuations and thus non-zero amplitudes. Studies (see e.g. Sawangwit et al. 2009; Thomas, Abdalla & Lahav 2011b) have found apparent excesses in the clustering strength at scales larger than 100 h\(^{-1}\) Mpc. Thorough studies are thus necessary to determine any potential sources of systematic error that could cause spurious fluctuations in the galaxy density field.

In this paper, we investigate the observational realities that may cause fluctuations in the observed density of galaxies when modelled incorrectly. These include stellar contamination and masking, Galactic extinction, sky brightness, seeing, airmass and offsets in photometric calibration. The effect of stellar contamination in a galaxy sample is well documented (see e.g. Myers et al. 2006; Thomas et al. 2011b; Crocce et al. 2011b). Stars may also cause a systematic effect on the number density of objects by occulting a small fraction of the sky. This area is of the order of 1 millionth of a square degree per star, but with tens of millions of stars, becomes substantial, given the precision to which clustering measurements can now be made.

Galactic extinction requires that magnitudes be corrected for the effect of dust in our Galaxy. It has been noted several times (e.g. Scranton et al. 2002; Myers et al. 2006; Ross, Brunner & Myers 2006; Ho et al. 2008; Wang & Brunner, in preparation) that errors in this correction may cause a systematic effect on the galaxy density field, as the effective depth of a survey would fluctuate. Further, constant (extinction-corrected) magnitudes have different fluxes (since the flux is directly related to the magnitude before extinction corrections). This implies that the expected magnitude error will vary as a function of the Galactic extinction. Airmass has a similar effect – this simply refers to the path-length of the photons through our atmosphere to the telescope, normalized to unity for observations at the zenith where it is minimized. At higher airmass, less photons reach the detector because more are scattered/absorbed in the atmosphere and thus the error on a measured magnitude will be related to the airmass. Finally, the observed flux of an object is more spread out at higher seeing – this increases the magnitude error and makes it more difficult to distinguish between stars and galaxies. Either of these seeing-dependent effects could cause spurious fluctuations in the observed density of galaxies.

We use data from the Sloan Digital Sky Survey (SDSS; York et al. 2000) eighth data release (DR8; Aihara et al. 2011) to identify and remove potential sources of systematic error on the angular clustering of objects selected to be luminous galaxies (LGs) with redshifts \( 0.4 < z < 0.7 \). Section 2 presents the data we use for our photometric redshift catalogue and the spectroscopic data we use to train the photometric redshifts we generate. Section 3 describes how we measure and model angular correlation functions. In Section 4, we investigate the fluctuations we find in the observed number density of LGs as a function of observational parameters and correct for the systematic errors these variations may impart. Section 5 explains how we train the photometric redshifts, the potential systematic effects we consider for this training, and the resulting photometric redshift catalogue that we generate. In Section 6, we present...
measurements of angular auto- and cross-correlation functions in slices of width \( \Delta z_{\text{phot}} = 0.05 \), test their consistency with a generic \( \Lambda \) cold dark matter (\( \Lambda \)CDM) model, and determine how the galaxy bias we calculate changes depending on the corrections we apply. We conclude with a summary of our results and a discussion of its greater implications in Section 7.

2 DATA

We use imaging data from the SDSS DR8 (Aihara et al. 2011) to create a photometric redshift catalogue of galaxies. This survey obtained wide-field CCD photometry (Gunn et al. 1998, 2006) in five passbands (u, g, r, i, z; e.g. Fukugita et al. 1996), amassing a total footprint of 14 555 deg\(^2\) data for which object detection is reliable to \( r \sim 22 \) (Aihara et al. 2011).

We use spectroscopy from the SDSS-III Baryon Oscillation Spectroscopic Survey (BOSS; Eisenstein et al. 2011) to obtain the spectroscopic redshifts, \( z_{\text{spec}} \), we use as a training sample for our photometric redshift catalogue. The BOSS is a spectroscopic survey that will target 1.5 million massive galaxies, 150 000 quasars and over 75 000 ancillary targets over an area of 10 000 deg\(^2\) (Eisenstein et al. 2011). BOSS observations began in 2009, and the last data will be acquired in 2014. The BOSS spectrographs (\( R = 1300–3000 \)) are fed by 1000 fibres in a single pointing, each with a 2 arcsec aperture. Each observation is performed in a series of 15-min exposures and integrated until a fiducial minimum signal-to-noise ratio is reached. This ensures an isotropic sample, complete to high redshift (\( z \sim 0.7 \)), resulting in a redshift completeness of \( \sim 97 \) per cent over the full imaging footprint.

2.1 Selecting imaging and redshift data

Our photometric catalogue has the same selection as the sample of BOSS targets chosen to have approximately constant stellar mass, denoted by ‘CMASS’, as described by Eisenstein et al. (2011). We select objects from the Catalog Archive Server (CAS) PhotoPrimary table\(^4\) identified as galaxies. We designate the subscript \( \perp \) to denote the SDSS uber-calibrated model magnitudes (Padmanabhan et al. 2008). The subscript \( \| \) denotes model magnitudes, where the model flux, \( \Phi_{\text{mod}} \), is defined as

\[
\Phi_{\text{mod}} = f_{\text{psf}} \Phi_{\text{dev}} + \Phi_{\exp}(1.0 - f_{\text{psf}}),
\]

where \( \Phi \) is the flux, the subscripts \( \text{dev} \) and \( \exp \) refer to the best-fitting de Vaucouleurs and exponential profiles, and \( f_{\text{psf}} \) is the fraction of the flux within the point spread function (PSF). The CMASS selection is then defined by

\[
17.5 < i_{\|} < 19.9, \quad (2)
\]

\[
r_{\perp} - i_{\|} < 2, \quad (3)
\]

\[
d_{\perp} > 0.55, \quad (4)
\]

\[
i_{\perp < 21.7}, \quad (5)
\]

\[
i_{\|} < 19.86 + 1.6(d_{\perp} - 0.8), \quad (6)
\]

where all magnitudes are corrected for Galactic extinction, \( i_{\perp} \) is \( i \)-band magnitude within a 2-arcsec aperture,\(^5\) and

\[
d_{\perp} = r_{\|} - i_{\|} - (g_{\|} - r_{\|})/8.0. \quad (7)
\]

Stars are further separated from galaxies by only keeping objects with

\[
i_{\text{psf}} - i_{\|} > 0.2 + 0.2(20.0 - i_{\|}), \quad (8)
\]

\[
z_{\text{psf}} - z_{\|} > 9.125 - 0.46z_{\|}, \quad (9)
\]

unless the object passes a ‘LOWZ’ cut defined by

\[
r_{\|} < 13.6 + c_{1}/0.3, \quad (10)
\]

\[
|c_{\perp}| < 0.2, \quad (11)
\]

\[
16 < r_{\|} < 19.6, \quad (12)
\]

where

\[
c_{1} = 0.7(g_{\|} - r_{\|}) + 1.2(r_{\|} - i_{\|} - 0.18) \quad (13)
\]

and

\[
c_{\perp} = r_{\|} - i_{\|} - (g_{\|} - r_{\|})/4.0 - 0.18. \quad (14)
\]

These target selection criteria produce a sample of just over 1.6 million objects, occupying over 11 000 deg\(^2\) of area on the sky. We refer to these objects as ‘LGs’. We cut this sample down to the main SDSS imaging area. We define this area as the data contained in HEALPix (Görski et al. 2005) pixels at \( N_{\text{side}} = 1024 \) (this resolution breaks the full sky into 12 582 912 equal-area pixels). Each pixel is assigned a weight, given its overlap with the imaging footprint (accounting for the area taken up by bright stars), and we include only pixels with weight at least 0.9. This process is described in detail in Ho et al. (in preparation). Further, we only use data with seeing (defined by the \( r \)-band PSF-FWHM, where FWHM stands for full width at half-maximum) less than 2.0 arcsec and Galactic extinction, \( E(B - V) < 0.08 \), as determined via the dust maps of Schlegel, Finkbeiner & Davis (1998). These cuts remove a large fraction of the data, leaving only 1065 823 objects. Their footprint is displayed in Fig. 1: 9 913 deg\(^2\), 2554 of which are in the southern stripes. A total of 282 687 of the objects are in the southern stripes, meaning their number density is 110.7 deg\(^{-2}\), while the number density in the north is 107.1 deg\(^{-2}\) – a 3.4 per cent difference.

We match the masked LGs to the BOSS CMASS spectra that had been observed and run through the spectroscopic pipeline up to 2010 November 11. This yielded a sample of 112 778 spectroscopic redshifts that are used to estimate photometric redshifts for our full sample. We find that 3.7 per cent of these spectroscopic objects are either stars or quasars (2.7 per cent stars and 1 per cent quasars). The percentage of quasars should be roughly constant across the sky, but the stellar contamination will be highly dependent on the proximity to the Galactic disc and centre. We find that the percentage of stars varies from 6 per cent at Galactic latitude \( b = 25^\circ \) to 1 per cent at \( b = 85^\circ \). Masters et al. (2011) find \( \pm 1 \) per cent point-source contamination by inspecting high-resolution Hubble Space Telescope images of BOSS CMASS targets in the COSMOS field (at \( b = 42^\circ \)).

We also use stars to investigate systematic effects. We select objects from PhotoPrimary that are identified as stars and have


\(^5\) We use an \( i_{\text{fbz}} \) limit of 21.7; although the limit has changed to 21.5 in current BOSS targeting, the limit was \( \leq 21.7 \) for all of the BOSS spectra in this study.
Ameliorating systematic uncertainties in \( w(\theta) \)

Figure 1. The density of objects in our catalogue, in equatorial coordinates (left-hand panel) and Galactic coordinates (right-hand panel), after masking for the imaging area, seeing, Galactic extinction and bright stars. This masked footprint occupies 9913 deg\(^2\). The density increases from blue to red, with blue representing a density that is less than 40 per cent of the average and red representing a density that is 120 per cent greater than the average.

17.5 < \( i_{\text{mod}} \) < 20.5. In total, this is over 84 million objects, but only 33 million reside within our masked footprint.

2.2 Star/galaxy probability

For the sample of BOSS spectra we use, 3.7 per cent of objects that are targeted as CMASS galaxies are spectroscopically classified as either stars or quasars. We use the software package ANNZ\(^6\) (Firth, Lahav & Somerville 2003) to identify stars, as in previous studies (e.g. Collister et al. 2007). Assigning galaxies a value of 1 and stars/quasars a value of zero, we divide our spectroscopic sample such that one quarter are placed into a training set, another one quarter into a validation set and the remaining half into a testing set. We then train ANNZ in order to classify galaxies, using the five SDSS model magnitudes and the parameters \( \ell_{\text{mod}}, \ell_{\text{psf}}, \ell_{\text{fib2}}, \ell_{\text{exp}}, R_{\text{pet}}, R_{\text{dev}}, R_{\text{exp}}, AB_{\text{dev}}, AB_{\text{exp}}, \ln L_{\text{exp}}, \ln L_{\text{pet}}, \text{ln} L_{\text{dev}}, \) where \( R \) is the radius, AB is the axial ratio, the subscript pet refers to the best-fitting Petrosian profile, and ‘\( \text{ln} L \)’ stands for the natural log of the likelihood. The values ANNZ returns, which we denote by \( p_{\text{sg}} \), are predominantly between 0 and 1, and when they are outside these bounds, we set them to 0 and 1, respectively. (This affects only 1 per cent of the objects and does not bias the overall probability distribution.)

We find that the star/galaxy training also does a good job of estimating the probability that an object is a galaxy. Fig. 2 displays the fraction of objects that are galaxies (\( p_{\text{gal}} \), as determined from their spectra) versus the value of the star/galaxy parameter, \( p_{\text{sg}} \). These two quantities are nearly identical, as can be seen by comparing to the dashed line. This implies we can treat \( p_{\text{sg}} \) as the probability that an object is a galaxy, allowing us to remove most of the effect of the stellar contamination. We note that the \( p_{\text{sg}} \) estimation benefits greatly from having a large training set distributed over 21:3 < |\( b \) | < 83:5 (less than 4 per cent of the objects in our catalogue lie outside these bounds). Unless otherwise noted, throughout we will be counting LGs by summing their values of \( p_{\text{sg}} \). For our full (masked) sample, the sum of \( p_{\text{sg}} \) is 1021 885, suggesting that 4.1 per cent of the objects are stars or quasars.

3 Measuring and modelling correlation functions

The primary focus of this work is to determine how systematics may affect the measured clustering signal. Therefore, we measure angular auto- and cross-correlation functions, \( w(\theta) \), of the density

\(^6\)http://www.homepages.ucl.ac.uk/~ucapola/annz.html
fields of LGs and of potential systematics. These statistics can be calculated extremely quickly\(^7\) and can be compared to cosmological models that are well tested by simulation.

3.1 Estimating \(w(\theta)\) and its covariance

We calculate \(w(\theta)\) using HEALPix pixels with \(N_{\text{side}} = 256\). Our mask has removed all data in pixels with weight \(< 0.9\) at the \(N_{\text{side}} = 1024\) resolution. Thus, given that the weights themselves are a good approximation of the fractional area of a pixel, the area per pixel for \(N_{\text{side}} = 256\) is well approximated by its weight, \(w_t\), multiplied by the area of the pixel. Therefore, the overdensity in pixel \(i\), \(\delta_i\), is given by

\[
\delta_i = n_i / \langle n w_t \rangle - 1,
\]

where \(n_i\) is the number of galaxies in pixel \(i\). For LGs and stars, \(\bar{n} = \sum n_i / \sum w_t\), while for observational parameters (such as Galactic extinction), \(\bar{n} = \sum A_i w_t / \sum w_t\), where \(A_i\) would be the average value of the observational parameter in pixel \(i\). The correlation function, \(w(\theta)\), is given by (see e.g. Scranton et al. 2002)

\[
w_{\theta,i}(\theta) = \sum_{i,j} \delta_{i}^p \delta_{j}^p \Theta_{\theta,i}(\theta) w_t \delta_{i}^p w_t \delta_{j}^p,
\]

where \(\Theta_{\theta,i}(\theta)\) is equal to 1 if pixel \(i\) is at an angular distance \(\theta \pm \Delta \theta\) from pixel \(j\) and zero otherwise, \(a = b\) represents an autocorrelation function, and \(a \neq b\) represents a cross-correlation function.

In order to compare \(w(\theta)\) measurements, we calculate jackknife errors, \(\sigma_{\text{jack}}\). We use 20 equal-area jack-knife regions. This is accomplished by selecting contiguous regions of HEALPix pixels whose weights sum to 1/20 of the total. The jack-knife errors are defined by (see e.g. Scranton et al. 2002; Myers et al. 2007; Ross, Brunner & Myers 2007)

\[
\sigma_{\text{jack}}^2(\theta) = \frac{1}{20} \sum_{i=1}^{20} \left[ w(\theta) - w_i(\theta) \right]^2,
\]

where \(w(\theta)\) is the measurement over the entire area and \(w_i(\theta)\) is the measurement when the \(i\)th jack-knife region is removed.

We calculate the covariance matrix that we use to compare our \(w(\theta)\) measurements to theoretical models by transforming theoretical \(P(k)\) to angular power spectra, and from the covariance of the angular power spectra to the \(w(\theta)\) covariance, \(C(\theta_1, \theta_2)\). The methods for doing this are outlined in, for example, Crocce, Cabré & Gaztañaga (2011a) and Ross et al. (2011b). Specifically, \(C(\theta_1, \theta_2)\) is given by equations (13)–(16) of Ross et al. (2011b), using a linear \(P(k)\). Croce et al. (2011a) have extensively tested these errors against mock catalogues, finding them to accurately reproduce the covariance in \(w(\theta)\) at linear scales, and we restrict this study to those scales. Further, at the large scales, estimations of the off-diagonal elements of the covariance matrix constructed using jack-knife methods have large statistical uncertainty and can therefore lead to unstatistic covariance matrices. Thus, we compare our measured \(w(\theta)\) to the model \(w(\theta)\) and \(C(\theta_1, \theta_2)\) in order to find the best-fitting model. In Section 6, we compare the theoretical and jack-knife uncertainties.

\[\text{Approximately, 15 min of total processing time using a single 2.53-GHz processor.}\]

3.2 Modelling

We compare our measurements to theory, assuming a flat ΛCDM cosmology with \(h = 0.7, \Omega_m = 0.274, f_b = 0.75, \Omega_b/\Omega_m = 0.18, n = 0.95\) and \(\sigma_8 = 0.8\) (as used in White et al. 2011), and a cosmic microwave background temperature of 2.725 K. We calculate the \(z = 0\) linear power spectrum using CAMB\(^8\) (Lewis, Challinor & Lasenby 2000). We account for the effects of structure growth via (see e.g. Seo & Eisenstein 2005; Croce & Soccoimmaro 2006)

\[
P(k, z) = D(z)^2 P(k, 0) e^{-\Omega_{19} D(z)^2 \delta_{1350-1373} w^2_{2417}, \text{(26)}}
\]

where \(D(z)\) is the linear growth rate; the exponential term accounts for the damping imparted by large-scale velocity flows. We derive \(s_8 = 5.27 h^{-1} \text{ Mpc}\) using the Zel’dovich approximation (Eisenstein, Seo & White 2007) for our fiducial cosmology. Such an approximation has been shown to be a good fit to the baryon acoustic oscillations feature in recent N-body simulation results (see e.g. Seo et al. 2010).\(^9\)

Given \(P(k, z)\), we Fourier transform to determine the isotropic three-dimensional real-space correlation function \(\xi_{\text{lin}}(r)\) (which is implicitly dependent on redshift). We then incorporate the effects of mode-coupling (see e.g. Croce & Soccoimmaro 2008; Sánchez, Baugh & Angulo 2008; Croce et al. 2011a) via

\[
x(r) = \xi_{\text{lin}}(r) + A_{\text{mc}} \xi_{\text{lin}}^{(1)}(r) \xi_{\text{lin}}^{(2)}(r),
\]

where \(\xi_{\text{lin}}^{(1)}\) is the derivative of \(\xi_{\text{lin}}\).

\[
\xi_{\text{lin}}^{(1)} \equiv \frac{1}{2\pi^2} \int P(k, z) j_1(kt) k \, dk,
\]

and for \(A_{\text{mc}}\), we use the value of 1.55 determined by Croce et al. (2011a).

We model the redshift-space correlation function as (Hamilton 1992)

\[
x^\prime(\mu, r) = \xi_0(\mu) P(\mu) + \xi_2(\mu) P_2(\mu) + \xi_4(\mu) P_4(\mu),
\]

where

\[
\xi_0(\mu) = \left( b^2 + \frac{2}{3} b f + \frac{1}{5} f^2 \right) \xi(\mu),
\]

\[
\xi_2(\mu) = \left( \frac{4}{3} b f + \frac{4}{7} f^2 \right) \left[ \xi(\mu) - \xi(\mu) \right],
\]

\[
\xi_4(\mu) = \frac{8}{35} \left[ \xi(\mu) - \frac{5}{2} \xi(\mu) - \frac{7}{2} \xi(\mu) \right],
\]

\(P_i\) are the Legendre polynomials,

\[
x^\prime = 3 r^{-3} \int_0^r x^\prime(r^2)^{3/2} \, dr',
\]

\[
x^\prime = 5 r^{-5} \int_0^r x^\prime(r^2)^{5/2} \, dr',
\]

\(b\) is the large-scale bias of the galaxy population being considered and \(\mu\) is the cosine of the angle to the line of sight. In order to calculate model \(w(\theta)\), we must project \(x^\prime(\mu, r)\) over the radial distribution of galaxy pairs in a particular sample (or samples in the case of cross-correlations):

\[
w(\theta) = \int dz_1 \int dz_2 n_1(z_1) n_2(z_2) \delta^8 [\mu, r(\theta, z_1, z_2)].
\]

\(\delta^8\) See http://camb.info

\(\text{This damping scale corresponds to } 7.45 h^{-1} \text{ Mpc, using the convention used in Eisenstein et al. (2007).}\)
where \( n_i \) is the normalized redshift distribution of sample \( i \) (and \( i = j \) for the autocorrelation). The galaxy separation \( r \) is a function of the angular separation of the galaxies, \( \theta \), and their redshifts \( z_1 \) and \( z_2 \) (as is \( \mu \)).

### 3.3 Correcting spurious clustering

Observational effects may cause spurious fluctuations in the number of observed LGs. As first derived (for large-scale clustering) in Ho et al. (in preparation), to first order, the systematic effect contributed by \( i \) observational parameters on the observed density field is given by

\[
\delta^i_g = \delta^i_g + \sum_i \epsilon_i \delta^i,
\]

(28)

where \( \delta^i_g \) is the overdensity of galaxies we observe, \( \delta^i \) is the true overdensity of galaxies and \( \epsilon_i \) assumes a linear relationship between the potential systematic and its effect on the observed overdensity of galaxies. According to equation (16), \( w(\theta) = (\delta^i \delta^j \Theta_1(\theta)) \). Thus,

\[
w^i_g(\theta) = w^i(\theta) - \sum_j \epsilon_j^2 w_j(\theta) - \sum_{i,j} 2 \epsilon_i \epsilon_j w_{i,j}(\theta) \tag{29}
\]

and

\[
w^o = \sum_j \epsilon_j w_{i,j}(\theta). \tag{30}
\]

We can measure \( w^i_g(\theta) \) (the autocorrelation function of our galaxy sample), \( w^i_g \) (the cross-correlation function of our galaxy sample with systematic \( i \)) and \( w_{i,j}(\theta) \) (the auto-cross-correlation function of the systematics). Thus, we always have \( i + 1 \) equations and unknowns \( \{ \epsilon_i \} \) and \( w^i_g(\theta) \) and we can therefore solve for \( w^i_g(\theta) \). We present the solutions for three systematics in Appendix B. We note that measuring the cross-correlation between observational parameters and galaxies in order to identify potential systematic errors has been applied to SDSS data since its early-data release (Scranton et al. 2002).

## 4 Systematic Effects on the Angular Distribution of Galaxies

Effects such as seeing, Galactic extinction and sky brightness may affect the number density of galaxies we select. Another important consideration is the presence of foreground objects. As shown in fig. 4 of Aihara et al. (2011), the presence of foreground objects has a significant effect on the number density of background objects one is able to detect.

### 4.1 Foreground stars

In order to investigate the effect of foreground stars on the observed density of LGs, we determine the number density of LGs in the immediate vicinity of stars within our masked footprint. In annuli of width 1 arcsec around each star, we determine the number density of LGs as a function of the maximum radius of the annulus. In the top left-hand panel Fig. 3, we present this measurement when considering stars with \( 17.5 < \text{i}_\text{mod} < 19.9 \) and dividing the LG sample into five \( \text{i}_\text{mod} \) bins. We find that the presence of a star has a significant effect on the ability to observe LGs with \( \text{i}_\text{mod} > 18.5 \) out to at least 10 arcsec (we note that there are only 22 000 LGs with \( \text{i}_\text{mod} < 18.5 \), making the results in this bin relatively uncertain). The effect remains nearly constant as a function of the \( \text{i}_\text{mod} \) magnitude, but it is strongest for the faintest sample (displayed in orange).

We also find that for \( i < 20.1 \), the \( i \)-band magnitude of the star does not produce a strong effect. This is shown in the top right-hand panel of Fig. 3, where we take the full LG sample and find the number density of these objects around six separate samples of stars that we have divided, based on model magnitudes, into bins between \( 19 < i < 20.5 \). We find similar results for the bins with \( 19 < i < 20.1 \) (the black, red, blue and green points and lines). The effect becomes significantly weaker for stars with \( 20.1 < i < 20.3 \). For the \( 20.3 < i < 20.5 \) bin, the effect is removed when the annuli have outer radii of at least 5 arcsec. When the outer radii are 3 and 4 arcsec, there is an excess of LGs. It is possible that this excess is caused by (resolved) binary stars—many stars are members of binary systems and thus there is an enhanced likelihood that an object within a few arcseconds from a star is also a star and therefore the stellar contamination rate in our LG sample will be higher around stars.

We find a deficit of LGs around stars with \( \text{i}_\text{mod} < 20.3 \) to at least 10 arcsec from the star. This suggests that the extended seeing disc of a star increases the sky noise in its vicinity and therefore makes object detection less likely. This implies that the effect should depend both on the seeing during the observation and the surface brightness of the object that might be detected. In the bottom left-hand panel of Fig. 3, we use the full LG sample and stars with \( 17.5 < i < 19.9 \) and divide the imaging area into six regions based on seeing (we note the median seeing in our masked footprint is 1.07 arcsec). As expected, we find that the deficit of LGs close to stars becomes greater as the seeing becomes more poor. However, there is still a significant deficit of LGs close to stars at all levels of seeing.

In the bottom right-hand panel of Fig. 3, we find the number density of LGs around stars with \( 17.5 < i < 19.9 \) when we divide the LGs into six bins based on the \( \text{i}_\text{mod} \) magnitude of the LG. We find dramatic differences, as we find a large excess for the brightest LGs (black, \( \text{i}_\text{mod} < 20.5 \)) and the largest deficit for the faintest LGs (magenta, \( \text{i}_\text{mod} > 21.5 \)). The \( \text{i}_\text{mod} \) magnitudes are a measure of the flux within a constant aperture and are therefore a measure of the surface brightness of the LG. Thus, as expected, we find that the presence of a star has the greatest effect on the objects with the lowest surface brightness. We find a large excess of LGs with \( \text{i}_\text{mod} < 20.5 \) between 2 and 5 arcsec from stars. We believe this excess caused by binary companions to the stars we are testing against, as the most compact objects will have the highest surface brightness (at constant \( \text{i}_\text{mod} \)) and are also most likely to be morphologically similar to stars.

Fig. 3 suggests that every star effectively removes a small amount of the imaging area. If this effect is not corrected for, we would expect an anticorrelation between LGs and stellar density. However, 4 per cent of the objects in our catalogue are stars, implying that, with no correction, there should be a positive correlation between LGs and stellar density. The bottom left-hand panel of Fig. 4 presents the relationship between LG density and the density of stars selected from the DR8 with \( 17.5 < \text{i}_\text{mod} < 19.9 \). When we equally weight every object (black), we see a slight decrease (~3 per cent across the full range) in the number of objects as the stellar density increases. This suggests the foreground presence of stars (which removes objects from our catalogue) dominates over the increase in objects we select (erroneously) as galaxies due to stellar contamination. If we instead weight each object by the probability that an object is a galaxy, \( p_\text{gal} \) (as estimated in Section 2.2; red), we find a significant and monotonic decrease (totalling 10 per cent) in the number of LGs as a function of stellar density. The upper portion of the bottom left-hand panel of Fig. 4 displays the fraction of our (masked) imaging area where the number...
The number density of galaxies we select around stars with $17.5 < r < 2000$ deg is minimized for $r < 2$. Beyond the occultation effect, there are an additional 6.3 million stars with $19.9$ magnitude bins. The top left-hand panel displays the results when we divide the galaxy sample into the noted $i_{\text{mod}}$-band magnitude bins. The top right-hand panel displays the case where we use the full galaxy sample and find the number densities around stars within the noted $i$-band magnitude bins. In the bottom left-hand panel, we display the results when the imaging regions are restricted to lie within the labeled seeing bounds. In the bottom right-hand panel, we divide the LGs into bins based on their $i$-band magnitude within a 2 arcsec aperture ($r_{\text{tot}}$). Errors are Poisson.

Figure 3. The number density of galaxies we select around stars with $17.5 < i_{\text{mod}} < 19.9$ (unless otherwise noted), divided by the average number density, in 1-arcsec-wide annuli, plotted against the maximum radius of the annulus. The top left-hand panel displays the results when we divide the galaxy sample into the noted $i_{\text{mod}}$-band magnitude bins. The top right-hand panel displays the case where we use the full galaxy sample and find the number densities around stars within the noted $i$-band magnitude bins. In the bottom left-hand panel, we display the results when the imaging regions are restricted to lie within the labeled seeing bounds. In the bottom right-hand panel, we divide the LGs into bins based on their $i$-band magnitude within a 2 arcsec aperture ($r_{\text{tot}}$). Errors are Poisson.
become more significant as limiting magnitudes are pushed fainter and there are thus more foreground objects that may have a masking effect. Foreground galaxies will cause the same problem, but will have a much smaller effect on the measured clustering, since at large scales, the angular clustering amplitudes of foreground galaxies are significantly smaller than those of stars.

4.2 Observational parameters

We find that the number density of LGs varies with observational parameters such as the Galactic extinction, seeing and brightness of the background sky. In Fig. 4, we display the number density, divided by the total average number density, of LGs as a function of the value of the potential systematic, for the cases where we equally weight each object (black), weight each object by its value of $p_{sg}$ (red), and weight each object by its value of $p_{sg}$ and subtract an area $A_{star}$ from each pixel for each star in the pixel (blue). In the top portion of each panel, we display the fraction of our imaging footprint which has a value of the potential systematic that is lower than the value on the $x$-axis, that is, the median value of the potential systematic is at $f_{area} = 0.5$. The median and inner/outer quartile values, within our masked footprint, of Galactic extinction, seeing, sky background and airmass are determined using this information and displayed in Table 1.

The bottom middle panel of Fig. 4 plots the relationship between the number density of LGs and the Galactic extinction in the $r$ band, $A_r$, [we use the $A_r$ values from the CAS, which are based on the Schlegel et al. (1998) dust maps and the relationship $A_r = 2.75E(B - V)$]. With equal weighting (black; we note these data are nearly indistinguishable from those represented in blue and green), the number density of LGs increases slightly as a function of $A_r$. The $A_r$ values and stellar densities are highly correlated (since they both trace the structure of our Galaxy), but this does result in $n/(n_{tot})(A_r)\text{ resembling the } h/h_{tot}(n_{star})\text{ relationship. Interestingly, the relationship flattens when we weight each object by } p_{sg}, \text{ but reverts to its original form when we additionally subtract } A_{star}.\text{ From the top portion of the panel, we can see that that the values of } A_r \text{ vary smoothly between } 0.03 < A_r < 0.2 \text{ and that its median value is } A_r = 0.08.

The autocorrelation function of $A_r$, is displayed in the red squares in the top panel of Fig. 5. The amplitudes are significantly non-zero and show a similar trend to the stars. Interestingly, the amplitudes of the Galactic extinction, $w(\theta)$, are significantly smaller than those of the star, $w(\theta)$, suggesting there is more structure to the distribution of stars in the Galaxy than to the dust in the Galaxy. The cross-correlation function of $A_r$ with the $p_{sg}$-weighted LGs (red squares in the bottom panel of Fig. 5) is negative (except at the largest scales), but consistent with zero at a majority of scales. Interestingly, the absolute values of this cross-correlation function are very similar.

Figure 4. Each of the six panels is divided such that the bottom portion displays the number density, divided by the average number density, as a function of the observational parameter. Individual points are connected by the solid lines and represented by the error bars, whose size is calculated assuming Poissonian statistics. Black represents equally weighted LGs (which can be both galaxies and stars) and red weighting each LG by the probability that it is a galaxy, $p_{sg}$. The results plotted in blue show the scenario when we weight each LG by $p_{sg}$ and subtract the effective area of stars, $A_{star}$, from each pixel for each star. Green displays the case where we change the selection criteria to $d_l > 0.5564$ for objects in the South, weight each LG by $p_{sg}$ and subtract $A_{star}$. Orange represents the application of iterative weights to the LG density field, in an attempt to remove all of the fluctuations. The top portion of each panel displays the fraction of the imaging area where the observational parameter is less than the value on the $x$-axis. From the top left-hand side to bottom right-hand side, the observational parameters are: sky background in $i$-band arcsec$^{-2}$ (sky); $i$-band airmass (airmass); the estimated offset in $d_l$ in mag ($d_l$ offset); number density of stars with $17.5 < i < 19.9$ ($n_{star}$); $r$-band Galactic extinction in mag ($A_r$); and $i$-band PSF-FWHM in arcsec (seeing). Errors are Poisson.
We also see significant changes in the number density as a function of the seeing. This result is shown in the bottom right-hand panel of Fig. 4. There is a 9 per cent decrease in the LG density between regions with seeing 1.2 arcsec and those with seeing 1.6 arcsec. We note that this is less than 25 per cent of the imaging area, as the upper quartile of seeing within our footprint is 1.19 arcsec. The reason for the decrease in LG number density in poor seeing is that the star/galaxy separation cut applied to BOSS targeting, given by equation (2.1), effectively changes. Increasing the seeing causes the PSF and model magnitudes to converge. The result is that in regions of poor seeing the two magnitudes are more similar – not because the object is too point-like, but rather because the PSF is too extended – and the cut is more likely to reject objects.

The green open triangles in the top panel of Fig. 5 present the measured $w(\theta)$ of the seeing. Its amplitudes are significantly smaller than either stars or $A_r$, though it is non-zero. This may be unexpected, as regions of similar seeing should follow the scanning pattern in the sky. However, in regions of the sky that were imaged multiple times (roughly 50 per cent of the DR8 footprint), the imaging with better seeing is chosen. This works to alleviate any large-scale pattern in the seeing within our footprint and also reduces the median seeing to 1.07 arcsec. The cross-correlation function of the seeing and LGs is displayed in the bottom panel of Fig. 5. The amplitudes are consistent with zero but transition from being negative at smaller scales to positive at larger scales.

The sky background has a complex relationship with measured flux errors, and we may therefore expect the number density of observed LGs to depend on the sky background. The top left-hand panel of Fig. 4 displays a 5 per cent increase in LG density between regions with a $i$-band sky background of 20.7 mag arcsec$^{-2}$ compared to those with a background of 20.5 mag arcsec$^{-2}$. This implies that the observed trend may be due to an increase in the average magnitude error scattering more objects into than out of our sample. However, 70 per cent of the footprint has a sky brightness between 20.5 and 20.0 mag arcsec$^{-2}$ (as shown in the top right-hand panel of Fig. 4) and the fluctuations are only $\sim$1 per cent in this range.

The autocorrelation function of the sky background is displayed in blue circles in the top panel of Fig. 5. It is significantly positive, but is only $\sim$1/20th of that of the stars. The cross-correlation of the sky background with the LGs, displayed in the bottom panel of Fig. 5, is significantly positive and $\sim$1/10th as large as the autocorrelation function of the sky background. This is the largest ratio between the auto- and cross-correlation functions of any of the potential systematics we measure. This suggests that the increase in LG number density between 20.7 and 20.5 mag arcsec$^{-2}$ is related to a significantly positive cross-correlation function.

For an object of given brightness, the number of photons that make it to the CCD depends on the airmass. One may therefore also expect that the magnitude error will depend on the airmass. The top middle panel of Fig. 4 displays the relationship between the number density of LGs and the airmass. We do not find smooth variations – rather we find a sharp increase in the number density where the airmass is approximately 1.35 and where it is greater than 1.5, and also a decrease where it is less than 1.05. This suggests that the fluctuations are not tied to the physical effect of the value of the airmass, but rather these specific values of the airmass are correlated with other observational parameters.

The median and inner/outer quartile values of observational parameters in our masked footprint are given in Table 1. The median seeing to 1.07 arcsec. The cross-correlation of the sky background with the LGs, displayed in the bottom panel of Fig. 5, is significantly positive and $\sim$1/10th as large as the autocorrelation function of the sky background. This is the largest ratio between the auto- and cross-correlation functions of any of the potential systematics we measure. This suggests that the increase in LG number density between 20.7 and 20.5 mag arcsec$^{-2}$ is related to a significantly positive cross-correlation function.

An object of given brightness, the number of photons that make it to the CCD depends on the airmass. One may therefore also expect that the magnitude error will depend on the airmass. The top middle panel of Fig. 4 displays the relationship between the number density of LGs and the airmass. We do not find smooth variations – rather we find a sharp increase in the number density where the airmass is approximately 1.35 and where it is greater than 1.5, and also a decrease where it is less than 1.05. This suggests that the fluctuations are not tied to the physical effect of the value of the airmass, but rather these specific values of the airmass are correlated with other observational parameters.

Table 1. The median and inner/outer quartile values of observational parameters in our masked footprint.

<table>
<thead>
<tr>
<th>Parameter</th>
<th>Median</th>
<th>Inner/outer quartile</th>
</tr>
</thead>
<tbody>
<tr>
<td>$A_r$</td>
<td>0.082 mag</td>
<td>0.053, 0.126 mag</td>
</tr>
<tr>
<td>Seeing</td>
<td>1.07 arcsec</td>
<td>0.96, 1.19 arcsec</td>
</tr>
<tr>
<td>Sky background</td>
<td>20.27 mag</td>
<td>20.43, 20.11 mag arcsec$^{-2}$</td>
</tr>
<tr>
<td>Airmass</td>
<td>1.16</td>
<td>1.08, 1.26</td>
</tr>
</tbody>
</table>

in amplitude to those of the cross-correlation function we measure between $A_r$ and the LGs when we subtract the effective area of stars — even though the $\hat{n}/\hat{n}_0(A_r)$ relationship displays a significant change between the two treatments, we find no evidence for a systematic effect on the measured clustering.

Figure 5. Top panel: the autocorrelation functions of the density field of the stars (black triangles), $r$-band extinction ($A_r$; red squares), $i$-band sky background (sky; blue circles), $i$-band PSF-FWHM (seeing; green open triangles), $i$-band airmass (orange open squares) and the estimated offset in $d_\perp$ (magenta open circles). Bottom panel: the same observables, but cross-correlated with the stars (black triangles), $r$-band extinction ($A_r$; red squares), $i$-band sky background (sky; blue circles), $i$-band PSF-FWHM (seeing; green open triangles), $i$-band airmass (orange open squares) and the estimated offset in $d_\perp$ (magenta open circles). The top middle panel of Fig. 4 displays the relationship between the two treatments, we find no evidence for a systematic effect on the measured clustering.
The autocorrelation function of the airmass and its cross-correlation function with LGs (orange open squares in Fig. 5) are quite similar to those of the sky background, especially at scales greater than 4°. Further, the geometric mean of the sky and airmass autocorrelation functions is nearly identical to their cross-correlation function. This suggests that the two fields are nearly fully co-variant in terms of the information they provide on the large-scale clustering of LGs. One might expect that the two would be related, as the airmass and, in general, the sky background are higher closer to the horizon. (The sky background should also depend on, for example, the phase of and proximity to the Moon and the azimuthal angle.) However, it is only the large-scale patterns that are similar – the local effects on the density field (as displayed in Fig. 4) clearly differ.

Finally, we use the results of Schlafly et al. (2010), who found colour offsets (caused by some combination of errors in the Galactic dust map and/or photometric calibration errors) for SDSS data based on the blue tip of the stellar locus, to make a map of the offset in $d_\perp$. We note that $\sim 15$ per cent of the imaging in the South was not available at the time these maps were made and that one may expect the colour of the blue tip to vary with the average metallicity of the stars that are used (which will vary as a function of position in the Galaxy). Regardless, any fluctuations we find may be important. We test against the implied offset in $d_\perp$, as small changes in $d_\perp < 0.55$ cut have a large effect on the number of objects we select into our sample (see Section 4.4). We find there to be slight excess in the number of LGs we find at both low and high values of the offset (displayed in the upper right-hand panel of Fig. 4). The autocorrelation of the $d_\perp$ offset is significant and $\sim 1/10$th that of $A_r$, but its cross-correlation function with the LGs is consistent with zero at nearly all of the scales we measure (both are displayed using magenta open circles in Fig. 5).

4.3 Eliminating systematic errors

We have investigated six potential sources of systematic errors (foreground stars, Galactic extinction, seeing, sky background, airmass and photometric offsets) and have found different fluctuations in LG density associated with each source. The autocorrelation functions of these potential systematics and their cross-correlation functions with the LGs suggest that stars have the greatest potential to cause systematic deviations in the measured clustering, and that we may have to worry about sky background fluctuations as well.

There are at least three procedures one can use to correct for these sources of potential systematic error. The first is to mask an area of the sky based on the value of the observational parameter. For instance, we have already masked areas with $(B - V) > 0.08$ and seeing $> 2.0$ arcsec. As we have described in Section 4.1, masking may be effective for removing the effects of foreground stars. However, for the other potential systematics, there will remain fluctuations in the number density of LGs, no matter the value of the cut we make on the systematic.

The second option is to find the combination of weights one can apply to remove the fluctuations one finds in the LG number density. This application is straightforward in the case that the effects are uncorrelated – each galaxy would just be weighted by the reciprocal of the function plotted in the bottom panels of Fig. 4. However, we find a significant correlation between the effects, making this process non-trivial.

The correlation between possible systematics can be accounted for by iteratively applying the weights. For instance, one may find the weights based on stellar density, $W_{\text{star}}(n_{\text{star}})$, by taking the reciprocal of what is plotted in red squares in Fig. 4 and then find $\bar{n}/n_{\text{star}}(A_r)$ while applying $W_{\text{star}}$ to the density field, the reciprocal of which is (the independent) $W(A_r)$. One may then proceed likewise through all potential systematics. The disadvantage to this approach is that it assumes each effect is fully separable (i.e. we can express $W[n_{\text{star}}, A_r] = X[n_{\text{star}}, V][A_r]$) and in the (realistic) case that this is not 100 per cent true; the order with which the weights are determined will matter. The advantage is that this method does not require a linear relationship between the potential systematic and the LG density fields and that it is straightforward to apply to as many potential systematics as can be identified. The resulting $\bar{n}/n_{\text{star}}(\text{sys})$ relationships when we determine the weights iteratively, in the order $n_{\text{star}},$ airmass, seeing, $A_r$, $d_\perp$ offset, sky, are displayed in orange in Fig. 4. Only for $n_{\text{star}}$ does the effect of applying subsequent weights cause a significant deviation from $\bar{n}/n_{\text{star}}(\text{sys}) = 1$. Hereinafter, we will refer to the application of these weights as the ‘Weights’ method.

The third option is to use the cross-correlation technique described in Section 3.3 to estimate and eliminate the spurious signal imparted by any number of observational parameters. We will refer to this method as the ‘Corr’ technique. The top panel of Fig. 6 displays the magnitude of the correction, calculated as described in Section 3.3, for different combinations of observational parameters. The correction for the stars alone (black triangles) decreases from $\sim 10^{-1}$ to $\sim 4 \times 10^{-4}$ from 1° to 20°. Additionally correcting for sky background (blue circles) marginally increases the correction at large scales but increases the correction by $\sim 30$ per cent at 1°. Adding seeing (red squares) or $A_r$, (green stars) corrections has only a marginal effect, which is most notable at small scales.

In the bottom panel of Fig. 6, the value of $\epsilon$ (as defined in Section 3.3) is displayed as a function of angle for stars (black triangles), sky background (blue circles), $A_r$ (red squares), seeing (open green triangles) and airmass (open orange squares). The correction we apply requires that $\epsilon$ be constant. The solid lines display the best-fitting (constant) value of $\epsilon$. As can be seen, in every case, a constant value of $\epsilon$ is well within the error bars, suggesting no need for higher order corrections. The values of $\epsilon$ are slightly more constant for sky background than for airmass, and we have found that they both trace the same large-scale clustering pattern. For this reason, we use only the sky background when calculating corrections.

Unless we note otherwise, in all cases, we measure the angular autocorrelation function of LGs, $w(\theta)$, by weighting each object by the value of $p_{\text{sg}}$. This means that instead of counting each LG equally, a LG is counted as $p_{\text{sg}}$, and thus, at large smoothing scales, the estimated overdensity of LGs should be the true (observed) overdensity of LGs. In principle, this should remove the contamination of stars, leaving only their systematic masking effect. We display this $p_{\text{sg}}$-weighted measurement of $w(\theta)$ with no corrections, multiplied by $\theta$, for all the LGs within our (masked) imaging area with black triangles in the left-hand panel of Fig. 7. The amplitudes at large scales are quite large, given that generic models predict $w(\theta) \sim 0$ for $\theta > 5'$.

Subtracting $A_{\text{star}}$ for each star within a pixel (blue circles in the left-hand panel of Fig. 7) significantly reduces the large-scale amplitudes of $w(\theta)$. Notably, this result is virtually identical to what we obtain when we do not subtract $A_{\text{star}}$ but instead apply the Corr technique when accounting for stars, as displayed with red squares in the left-hand panel of Fig. 7 (the magnitude of this correction is displayed with the black triangles in Fig. 6). This suggests that either method can be used, and the approach one uses should depend on its ease with respect to the task at hand. Notably, the jack-knife errors are smaller when we subtract $A_{\text{star}}$. 

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The black curve plotted in Fig. 7 displays the expected clustering for our fiducial ΛCDM cosmology and a bias of 2.0 (calculated as described in Section 3.2). This model appears generally consistent with all the measurements at small scales, but at scales greater than 2°, the uncorrected measurements are significantly greater. We note that the feature in the model at ~3:5 is due to the baryon acoustic oscillations present in our fiducial P(k). Including corrections for stars and sky background appears to make the measurements generally consistent with the assumed cosmological model, although all but one of the measurements remains larger than the model between 3° and 12°.

### 4.4 North and South Galactic caps

The DR8 imaging data are separated into two distinct regions; in Galactic coordinates, these regions can be separated into $b > 0°$ (North) and $b < 0°$ (South) (see Fig. 1). The fact that these regions are spatially separated makes them more prone to calibration errors, for example, one might expect uncertainty in the relative zero-points of one or more bands, given the lack of continuous photometry connecting the two regions. Schlafly et al. (2010) and Schlafly & Finkbeiner (2010) have estimated the level of colour offset between the North and South in the SDSS. Schlafly et al. (2010) and Schlafly & Finkbeiner (2010) attribute these differences to either calibration errors or errors in the Galactic extinction corrections (or a combination of both). Using results of the ‘spectrum’-based method (which is less sensitive to changes in the metallicity of stars than the ‘blue-tip’ method) listed in the second row of Table 6 of Schlafly & Finkbeiner (2010), one can infer that the values of $d_\perp$ (a combination of $g - r$ and $r - i$ colours defined by equation 7) that we calculate are offset by 0.0064 mag between the North and South (the ‘blue-tip’ method yields a similar offset of 0.0045 mag). These results suggest that, assuming the values in the North are the true values, we should subtract 0.0064 from the values we calculate in the South to obtain a better estimate of their $d_\perp$ values.

The inferred offset in $d_\perp$ between the North and South appears small, and given the difference between the ‘spectrum’- and ‘blue-tip’-based methods, the uncertainty on the correction may be relatively large. However, it is instructive to determine the effect a 0.0064 mag offset in $d_\perp$ would have on our sample. If we change the cut such that we accept only objects with $d_\perp > 0.5564$ in the South (while using the fiducial cut in the North), we remove 5172 objects from our sample. This reduces the number density in the South to 108.7 deg$^{-2}$ – which is still 1.5 per cent greater than the number density in the North. If we weight each object by $p_{sg}$ when calculating the number densities (which should provide a better estimate of the true number density of galaxies), the number density in the South increases to 103.2 deg$^{-2}$ and in the North it becomes 103.1 deg$^{-2}$. Any uncertainty in the corrections we have made is almost certainly larger than this 0.1 deg$^{-2}$ difference in number density. The $\bar{n}/\bar{n}_{sys}(sys)$ relations we obtain when we use the $d_\perp > 0.5564$ cut in the South, subtract $A_{star}$, and weight by $p_{sg}$ are displayed in green in Fig. 4. This does not cause major changes, but
Ameliorating systematic uncertainties in $w(\theta)$

Figure 7. The measured angular autocorrelation function, $w(\theta)$, measured by weighting each LG by $p_{LG}$, multiplied by $\theta$ for our full sample of LGs. In the left-hand panel, the black triangles show the measurements with no corrections and the fiducial mask, the red squares mark the measurement when we correct for stars (as described in Section 3.3) and the blue circles display the measurement when we make the $A_{star}$ correction. In the right-hand panel, the open green triangles display the measurement we obtain when we correct for stars and sky background ($C_{star,sky}$), the open orange squares display the results when we make the $A_{star}$ correction and additionally correct for sky background ($-A_{star}, C_{sky}$), the open orange squares show the $w(\theta)$ we measure when we apply iterative weights to the LG density field (Weights) and the cyan stars show the result when we apply a $C_{star}$ correction in addition to the Weights. The solid line displays the model $w(\theta)$ for our assumed cosmology and $b=2$.

Figure 8. The measured angular autocorrelation functions ($w(\theta)$) for the full LG sample (black triangles), LGs in the Northern Galactic cap (blue circles), LGs in the Southern Galactic cap (open green triangles) and the LG sample we obtain when we impose the cut $d_\perp > 0.5564$ for objects in the South Galactic cap (red squares). In each case, we subtract an area $A_{star}$ for each star in each pixel and correct for sky brightness.

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the relationships with airmass, $A_r$ and $d_\perp$ offset all become closer to 1.

Given the colour offsets and the change in number density they imply, we might expect differences in the clustering of the LGs in the North and South. Fig. 8 displays the $w(\theta)$ we measure when we split the LG sample into North (blue circles) and South (open green triangles) samples and apply the $A_{star}, C_{sky}$ correction. Indeed, the clustering is different in the two regions, as the measurements in the South are smaller than those in the North. However, at scales less than 30°, the $w(\theta)$ of the full sample (black triangles) simply appears to be the weighted average of the two samples. At the largest scales ($\theta > 30'$), this is not the case, suggesting that the colour offset may cause a systematic effect on the measurements at the largest scales (we note that the sky background correction may have minimized this potential systematic effect, confining it to these large scales).

We have found that using the cut $d_\perp > 0.5564$ in the South removes the asymmetry in the number density of LGs in the North and South. We therefore measure $w(\theta)$ of the LG sample after making this cut, which is plotted with red squares in Fig. 8. The result is quite similar to the result obtained using the fiducial cuts (black triangles), but the amplitudes at the largest scales are reduced and appear to be closer to the weighted average of the North and South. Interestingly, the size of the sky brightness correction depends strongly on our particular treatment of the North and South. We find $\epsilon_{sky} = 0.113$ for the full sample, $\epsilon_{sky} = 0.068$ when we use the $d_\perp > 0.5564$ cut in the South, $\epsilon_{sky} = 0.027$ in the North sample and $\epsilon_{sky} = 0.18$ for the South sample. This suggests that the systematic effect of sky brightness is predominantly a feature of the Southern imaging.
4.5 Summary of angular fluctuations

The results presented throughout this section suggest that stars cause major systematic errors on the clustering of SDSS DR8 LGs, and sky brightness may also cause significant errors. We have investigated variations in number density caused by Galactic extinction, seeing, airmass and colour offsets, but found them to have minor effects. Perhaps most importantly, we have identified two separate ways to correct for systematic variations in the number density of galaxies caused by any potential systematic that can be quantified and turned into a map on the sky, and for the stars we have identified three separate ways to correct for their systematic effects.

We note that other catalogues constructed from other imaging surveys, other SDSS data or even subsets of the LG data will not necessarily display the same relationships we have found in this section. The tests we have performed must be repeated for any sample one uses to measure clustering. We further note that the systematics we investigate are by no means a complete list – there are likely to be effects we have not thought of.

5 CONSTRUCTING THE PHOTOMETRIC REDSHIFT CATALOGUE

We measure photometric redshifts for our LG sample using the artificial neural network based photometric redshift estimator ANNz (Firth et al. 2003). ANNz has been proven to yield accurate and precise zphot estimates when the training sample is representative of the full data set (see e.g. Collister et al. 2007). The results of Abdalla et al. (2008) and Thomas et al. (2011a) suggest that neural network based photometric redshift estimators (such as ANNz) are the most accurate in this specific situation. Our training sample consists of 112 778 BOSS CMASS objects with spectroscopic redshifts. This large training sample provides unprecedented ability to ensure the training sample is representative of our imaging data, while accounting for fluctuations in observing conditions.

Fig. 9 displays the normalized redshift distributions for data with \( \langle A_r \rangle = 0.08 \) and 0.13 (which splits the sample approximately in half). There is a significant difference, as the objects in areas of the sky with low Galactic extinction (red) have a larger median redshift and more galaxies in the high-redshift tail of the distribution. This result suggests that we may obtain better zphot estimates if we include the \( A_r \) values in the training, which we can do because the training data cover the entire range of Galactic extinction found in our full sample. This finding implies that Galactic extinction may be an important systematic when the clustering of the BOSS spectroscopic sample is analysed.

We have also found fluctuations in the spectroscopic redshift distributions with seeing and sky background; these fluctuations will be studied in detail in Ross et al. (in preparation). Despite the fact that the training consists of over 100 000 objects, we do not find that it adequately covers the range in sky background or seeing which would be required to include these parameters in the photometric redshift training. Instead, we repeat the tests we performed on the whole sample in Section 4 on samples in zphot slices in Section 6.

5.1 Photometric redshift training

We train ANNz to estimate photometric redshifts for our LGs using similar methods to those of Collister et al. (2007). We randomly divide our sample of CMASS spectra (keeping only objects spectroscopically confirmed to be galaxies) such that one quarter of the objects are designated as a training set, a separate one quarter as a validation set and the remaining half of the objects as a testing set (as is done in Collister et al. 2007). We use the dereddened model magnitudes in the \( g, r, i, z \) SDSS imaging bands, and their errors. We do not use the \( u \) band because the results of Schlafly et al. (2010) suggest there may be significant variations in the true \( u - g \) colour over the SDSS imaging area, and the \( u \) band only significantly aids \( z_{\text{phot}} \) estimation for the bluest galaxies in our sample.

We test three different training samples that use the following input parameters:

(i) Only the \( g, r, i \) and \( z \) (dereddened) model magnitudes and their errors

(ii) Including the Galactic extinction in the \( i \) band, \( A_i \), in addition to the model magnitudes

(iii) Including the ratio of major to minor axes, \( a/b \), of the ellipse corresponding to the best-fitting exponential profile in the \( i \) band in addition to the magnitude and \( A_i \) information

In case (i), the rms difference between \( z_{\text{spec}} \) and \( z_{\text{phot}} \) is 0.0610 for the full sample; this reduces to 0.0512 for galaxies with \( c_1 > 1.6 \). We find that 92 per cent of the LGs pass this \( c_1 > 1.6 \) restriction which was used by previous studies, such as Collister et al. (2007). Such a restriction ensures a strong 4000 Å break for galaxies at our target redshifts (\( 0.4 < z < 0.7 \)), and Masters et al. (2011) find that this cut removes most of the galaxies that would be morphologically classified as late type from the CMASS sample. For case (ii), we find that including the \( A_i \) information produces insignificant improvements, as the rms values become 0.0609 and 0.0511, respectively. Case (iii) significantly improves the rms for objects with \( c_1 < 1.6 \), as the overall dispersion decreases to 0.0585 and we find a slight improvement for the \( c_{||} > 1.6 \) galaxies, as the rms decreases to 0.0506.

Because the dispersion values suggest, there is a strong correlation between the value of \( c_{||} \) and the accuracy with which we can estimate \( z_{\text{phot}} \). We display the relationship between the rms dispersion in our

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\[ \text{Figure 9. The normalized redshift distributions of BOSS CMASS spectra when splitting into regions with } r \text{-band Galactic extinction, } \langle A_r \rangle = 0.08 \text{ (red) and 0.13 (black).} \]

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testing set versus $c_1$ in the middle panel of Fig. 10 for our three different training samples. The obtained relationship is extremely similar whether we include $A_i$ [case (ii), red squares] or we do not [case (i), black triangles]. Including $a/b$ (case iii) reduces the rms for objects with $c_1 < 1.8$. However, all three cases show that the most accurate $z_{\text{phot}}$ estimates are obtained when $c_1 > 1.8$.

We also find a significant correlation between the accuracy of the $z_{\text{phot}}$ estimates and $a/b$. Masters et al. (2011) has discovered that $\sim5$ per cent of CMASS objects are edge-on spiral galaxies where effects of dust obscuration are likely to be significant. Logically, this likelihood is correlated with the axial ratio. These dust-obscured spirals tend to be at lower redshifts than the majority of CMASS objects (while having similar colours, see Yip et al. 2011 for a full study of the effects of inclination on photometric redshift estimates), and thus the accuracy of the $z_{\text{phot}}$ estimate and $a/b$ are related. We present this relation in the right-hand panel of Fig. 10, which shows that it is a smooth function of $\log_{10}(a/b)$ for each of our three training samples. Including $a/b$ in the training improves the $z_{\text{phot}}$ accuracy for the largest values of $a/b$. The values of $a/b$ are correlated with $c_1$, since it is disc galaxies (which are generally blue galaxies in $c_1$) that have the highest values of $a/b$. However, we find similar relationships (though not as strong) when this correlation is accounted for.

The dispersion is also correlated with the estimated $z_{\text{phot}}$, as illustrated in the left-hand panel of Fig. 10. Each of the three training cases results in similar relationships. Including $a/b$ [case (iii), blue circles] makes the largest difference for $z_{\text{phot}}$ estimates between 0.45 and 0.6. We see only minor differences between cases (i) (model magnitudes only, black triangles) and (ii) (including $A_r$, red squares).

The ANNz output includes a photometric redshift error estimate, which we denote by $\sigma_{z_{\text{phot}}}$. These reported errors are correlated to the actual dispersion in $z_{\text{phot}}$ versus $z_{\text{spec}}$, but they underestimate it by a factor of $\sim66$ per cent (as can be determined by comparing the average value of $\sigma_{z_{\text{phot}}}$ and $\sqrt{\langle (z_{\text{phot}} - z_{\text{spec}})^2 \rangle}$ for any particular testing set). These estimated errors do not recover the trends we discover between the rms of $z_{\text{spec}} - z_{\text{phot}}$ and $c_1$ or $a/b$ (which are displayed in the middle and right-hand panels of Fig. 10). Thus, the true uncertainty on any individual $z_{\text{phot}}$ estimate is a linear combination of the estimated error, $c_1$ and $a/b$. In Section 5.3, we describe how we combine this information in order to estimate the redshift distributions of the photometric redshift samples we use.

Fig. 11 presents the overall redshift distribution of spectroscopic galaxies in our testing set (solid black line). The coloured lines display the spectroscopic redshift distributions of testing set galaxies in slices of width $\Delta z_{\text{phot}} = 0.05$ from 0.4 to 0.7, when we estimate $z_{\text{phot}}$ using case (iii) (including $A_i$ and $a/b$ in the training sample). In all cases, the dashed lines represent galaxies with $c_1 > 1.6$. These distributions suggest that, if one wishes to use slices of width $\Delta z_{\text{phot}} = 0.05$, the bins $0.45 < z_{\text{phot}} < 0.5$, $0.5 < z_{\text{phot}} < 0.55$, $0.55 < z_{\text{phot}} < 0.6$, and $0.6 < z_{\text{phot}} < 0.65$ contain most of the information, as the bins $0.4 < z_{\text{phot}} < 0.45$ and $0.65 < z_{\text{phot}} < 0.7$ have their true redshifts almost entirely within the adjacent $z_{\text{phot}}$ slice.

5.2 Photometric redshift catalogue

We construct a photometric redshift catalogue using the objects selected as described in Section 2, and using the ANNz training which includes both Galactic extinction and axial ratios (case iii). We did not find any significant difference in the accuracy of the $z_{\text{phot}}$ estimates when we added $A_i$ information to the training (case ii).
However, we do find a large difference in the full \( z_{\text{phot}} \) distributions. In particular, we find that the asymmetry between the North and South increases as a function of \( z_{\text{phot}} \). For 0.6 < \( z_{\text{phot}} \) < 0.65, \( c_b > 1.6 \) and weighting by \( p_{sg} \), we find a 7.5 per cent larger number density of LGs in the South when we do not include \( A_i \) values in the training, and only a 4.9 per cent larger number density when we do include \( A_i \).

In Fig. 12, we display the ratio of the number of objects in the South to the number of objects in the North as a function of \( z_{\text{phot}} \). For \( z_{\text{phot}} > 0.55 \) and \( z_{\text{phot}} < 0.46 \), there is a significant excess in the number of objects in the South. When we apply the \( d_\perp > 0.5564 \) cut to objects in the South, there is a significant decrease in the number of objects in the South with \( z_{\text{phot}} < 0.46 \); however, we find almost no change at larger photometric redshifts. This is due to the fact that objects that are assigned larger \( z_{\text{phot}} \) have larger \( d_\perp \) values. In fact, we find a linear relationship between the average \( z_{\text{phot}} \) and \( d_\perp \) given by \( z_{\text{phot}} = 0.53 d_\perp \). Inserting the \( d_\perp = 0.0064 \) offset for objects in the South (as suggested by Schlafly & Finkbeiner 2010) yields a bias of \( \Delta z = 0.0034 \) for objects in the South. When we subtract 0.0034 from each \( z_{\text{phot}} \) in the South, we find that the ratio between the number of objects in the South and the number of objects in the North (the blue curve in Fig. 12) becomes nearly constant as a function of \( z_{\text{phot}} \). This is because the \( z_{\text{phot}} \) of objects in the South increases as a function of \( z_{\text{phot}} \).

Fig. 11 implies that the majority of the cosmological information will be located within four \( z_{\text{phot}} \) bins 0.45 < \( z_{\text{phot}} \) < 0.5 (which we denote by bin 1), 0.5 < \( z_{\text{phot}} \) < 0.55 (which we denote by bin 2), 0.55 < \( z_{\text{phot}} \) < 0.6 (which we denote by bin 3) and 0.6 < \( z_{\text{phot}} \) < 0.65 (which we denote by bin 4). The characteristics of each bin are summarized in Table 2. The training further suggests that we can only obtain accurate \( z_{\text{phot}} \) estimates for objects with \( c_b > 1.6 \); thus, we also make this cut in each bin.

5.3 Estimating true redshift distributions

To properly analyse any angular clustering measurement, one must know the true redshift distribution of the galaxies being used. This task is made relatively simple for the photometric redshift catalogue we produce, as we expect the distributions to be similar to those of the training sample. However, the match is not perfect, and blindly assuming that the full catalogue has the same distribution as the training sample would be folly – differences between the catalogues must be accounted for. Based on our testing sample, we found that the actual dispersion between the photometric and spectroscopic redshifts was not only well correlated to the error estimate, but also subject to the values of \( c_b \) and \( a/b \). Thus, we can compare the distributions of photometric redshifts, error estimates, \( c_b \), and \( a/b \) in the full data set to that of the testing set and use this information to estimate the true redshift distribution in any \( z_{\text{phot}} \) slice.

For bin 1 (0.45 < \( z_{\text{phot}} \) < 0.5), the mean of the \( z_{\text{phot}} \) error estimated by ANNz, \( \sigma_{\text{ANNz}} \), is 0.0224, while it is slightly lower, 0.0222, for the testing set (recall that these estimates underestimate the actual \( \sqrt{(\langle z_{\text{phot}} - z_{\text{spec}} \rangle)^2} \) by ~66 per cent). The average \( c_b \) and \( a/b \) of the full bin 1 and the testing set subset of bin 1 agree within 0.3 per cent. We find the deviations in \( c_b \) are similarly small for the other three redshift bins. Overall this suggests that the true redshift distribution of bin 1 is slightly wider than the spectroscopic distribution, due to the fact that its \( \sigma_{\text{ANNz}} \) is 1 per cent larger than those for the testing set. Thus, referring to \( \sigma_{\text{ANNz}} \) as the true dispersion in the bin and \( \sigma_{\text{ANNz}} \) as the dispersion in the testing set, we estimate \( \sigma_{\text{ANNz}} = 0.0431 \), given that \( \sigma_{\text{ANNz}} = 0.0427 \). In Table 2, we list the \( \sigma_{\text{ANNz}} \) we measure from the testing set and the \( \sigma_{\text{ANNz}} \) we estimate for each photometric redshift bin.

For bin 2 (0.5 < \( z_{\text{phot}} \) < 0.55), the differences are more substantial. The value of \( \sigma_{\text{ANNz}} \) is 3 per cent larger for the full catalogue (0.0268 compared to 0.0260) and the average value of \( \log_{10}(a/b) \) is 2 per cent larger (0.170 compared to 0.166). Fig. 10 suggests a linear relationship between the photometric redshift dispersion and \( \log_{10}(a/b) \) for 0 < \( \log_{10}(a/b) \) < 0.3, that is, \( \sigma_{\text{ANNz}} \sim 0.05 + 0.067 \log_{10}(a/b) \), suggesting the overall error should be 3.5 per cent larger in bin 2 than for the testing set. The differences grow larger for bin 3 (0.55 < \( z_{\text{phot}} \) < 0.6); the value of \( \sigma_{\text{ANNz}} \) is 4 per cent larger (0.0307 compared to 0.0296) than for the testing set and the average value of \( \log_{10}(a/b) \) is 5 per cent larger (0.180 compared to 0.172), suggesting the errors in bin 3 are 4.6 per cent larger than in the testing set. We find similar differences for bin 4 (0.6 < \( z_{\text{phot}} \) < 0.65): the values of \( \sigma_{\text{ANNz}} \) are 0.0334 and 0.0320 and the average values of \( \log_{10}(a/b) \) are

<table>
<thead>
<tr>
<th>Bin</th>
<th>( z_{\text{phot}} ) range</th>
<th>( \sum_{i=1}^{N_{\text{phot}}} p_{tgi} )</th>
<th>( \sigma_{\text{ANNz}} )</th>
<th>( \sigma_{\text{ANNz}} )</th>
</tr>
</thead>
<tbody>
<tr>
<td>1</td>
<td>0.45 &lt; ( z_{\text{phot}} ) &lt; 0.5</td>
<td>214971</td>
<td>0.0427</td>
<td>0.0431</td>
</tr>
<tr>
<td>2</td>
<td>0.5 &lt; ( z_{\text{phot}} ) &lt; 0.55</td>
<td>258736</td>
<td>0.0427</td>
<td>0.0442</td>
</tr>
<tr>
<td>3</td>
<td>0.55 &lt; ( z_{\text{phot}} ) &lt; 0.6</td>
<td>248895</td>
<td>0.0501</td>
<td>0.0524</td>
</tr>
<tr>
<td>4</td>
<td>0.6 &lt; ( z_{\text{phot}} ) &lt; 0.65</td>
<td>150319</td>
<td>0.0601</td>
<td>0.0633</td>
</tr>
</tbody>
</table>

Table 2. The characteristics of the four photometric redshift (\( z_{\text{phot}} \)) bins we use, where \( \sigma_{\text{ANNz}} \) refers to the value of \( \sqrt{(\langle z_{\text{phot}} - z_{\text{spec}} \rangle)^2} \) in the testing set and \( \sigma_{\text{ANNz}} \) refers to the level of dispersion we infer for the full data set, using the methods described in Section 5.3.
The estimated (normalized) redshift distributions for the four labelled $z_{\text{phot}}$ slices, determined by sampling Gaussians around each spectroscopic LG in the testing data, as described in Section 5.3.

0.185 and 0.176, and we therefore expect the errors to be 5.4 per cent larger than in the testing set.

To correct for the differences between the testing set and full sample, we sample a Gaussian, for each spectroscopic redshift within the photometric redshift bin, of width such that the average dispersion in the bin increases to that which we expect. The dispersion we expect, $\sigma_\text{d}$, is related to the dispersion in the testing set, $\sigma_\text{t}$, and the width of the Gaussian, $\sigma_\text{g}$, via

$$\sigma_\text{d}^2 = \sigma_\text{t}^2 + \sigma_\text{g}^2.$$  \hfill (31)

We are assuming $\sigma_\text{g} = a \sigma_\text{t}$, where we described the process of determining $a$ in the previous paragraph. Therefore,

$$\sigma_\text{d}^2 = \sigma_\text{g}^2(a^2 - 1).$$  \hfill (32)

For bin 4, $a = 1.054$ (since we determined the dispersion should be 5.4 per cent larger for the full sample than for the testing set) and $\sigma_\text{g} = 0.06$, which yields $\sigma_\text{d} = 0.02$. We find that, with sufficient sampling, the resulting $n(z)$ are smooth up to steps of 0.001 in $\Delta z$. We display the $n(z)$ we obtain for our four bins in Fig. 13. In general, the displayed $n(z)$ are poorly fitted by distributions such as a Gaussian or a Lorentzian (especially at the tails). Thus, we use the plotted distributions, which are binned in steps of width 0.001 in redshift, and interpolate between these points as needed in order to obtain the $n(z)$ used in equation (27).

### 6 Clustering in Photometric Redshift Bins

#### 6.1 Auto- and cross-correlation function measurements

In order to investigate the photometric redshift catalogue, we have measured the angular auto- and cross-correlation functions of galaxies in the four photometric redshift bins summarized in Table 2. This will allow us to investigate how systematics affect particular photometric redshift bins and if the redshift distributions are the same as suggested by the training data.

Fig. 14 displays the measured autocorrelation functions for LGs, multiplied by $\theta$, in our four photometric redshift bins with no corrections (black triangles), applying the Corr technique for stars and sky background (calculated as described in Section 3.1; red squares, $C_{\text{star,sky}}$), subtracting the effective masked area per star, $A_{\text{star}}$, for every star in each pixel and apply the Corr technique for sky background (blue circles; $-A_{\text{star}}, C_{\text{sky}}$), applying weights based on the $\bar{r}/\bar{r}_{\text{rad}}(\text{sys})$ relationships iteratively determined in the order $r_{\text{star}}, m_{\text{ass}},$ seeing, $A_{\text{s}}$, $d_{\perp}$ offset, sky (open green triangles; ‘Weights’), and applying the cut $d_{\perp} > 0.55$ and subtracting 0.0034 from each photometric redshift for objects in the South while also applying the $-A_{\text{star}}, C_{\text{sky}}$ correction (open orange squares; ‘ΔSouth’). Correcting for either seeing or Galactic extinction makes negligible difference. For each bin, the displayed error bars are the jack-knife errors.

Interestingly, only bin 1 and bin 4 show any significant effect from sky background; for bins 1, 2, 3 and 4, the values of $e_{\text{sky}}$ for $C_{\text{star,sky}}$ are 0.098, 0.021, 0.034 and 0.137, respectively. This result is consistent with the assertion that the dependence on sky background is related to its effect on the magnitude errors. The lowest redshift bin should show the largest effect from objects scattering around the $d_{\perp} > 0.55$ cut (as can be inferred from the difference between the red and black curves in Fig. 12), and the highest redshift bin should show the largest effect from objects scattering across the faint magnitude limit.

For each of the measurements displayed in Fig. 14, we determine the best-fitting bias, $b$, given our fiducial cosmological model. In each panel of Fig. 14, the black curve displays the best-fitting model when fitted to the measurements with the $C_{\text{star,sky}}$ corrections applied. We fit to angular scales $1^\circ < \theta < 20^\circ$ (the equivalent physical separation for a $1^\circ$ separation is $33.2$ h $^{-1}$ Mpc at $z = 0.5$), for which there are 16 data points in each redshift bin. The best-fitting $b$ and the associated $\chi^2$ per degree of freedom ($\chi^2$/d.o.f.) are listed for each redshift bin and each of the five separate estimations of $w(\theta)$ in Table 3. Given that we are using a theoretical covariance matrix to compare between our measured and model $w(\theta)$, we have 15 d.o.f. regardless of the corrections that we apply. The covariance matrices assume that there is no added covariance due to systematics, and the corrections are an attempt to remove this covariance and allow proper comparison between measurement and model.

In every case, applying some form of correction reduces $\chi^2$/d.o.f. compared to the case when no corrections are applied. In each redshift bin other than bin 1, $\chi^2$/d.o.f. is greater than 3 when no corrections are applied. When corrections are applied, $\chi^2$/d.o.f. are all less than 2, and only for bin 2 are they significantly greater than 1. After each of the minimum $\chi^2$/d.o.f. reported in Table 3, we list, in parentheses, the $\chi^2$/d.o.f. obtained when we fit to a maximum scale of $60^\circ$ (which is the largest scale to which we measure $w(\theta)$) and keep the model the same as the best-fitting one for $1^\circ < \theta < 20^\circ$. This tests the consistency of the six measurements with $20^\circ < \theta < 60^\circ$. Notably, none of the $\chi^2$/d.o.f. values becomes significantly worse.

The most extreme results are obtained when the ΔSouth corrections are applied. For bin 2, only 0.8 per cent of $w(\theta)$ measurements consistent with our fiducial model would have $\chi^2$/d.o.f. greater than the value of 2.1 that we find, while for bin 4, we find $\chi^2$/d.o.f. = 0.38 and would expect 98.4 per cent of $w(\theta)$ measurements to have a greater value. As isolated cases, neither result is particularly remarkable. However, regardless of the Corr technique, the $\chi^2$/d.o.f. values for bin 2 are all greater than 1.8. This result is caused, in large part, by the $w(\theta)$ measurements at $\sim 2^\circ$, which are considerably smaller than the $w(\theta)$ predicted by our best-fitting model.
The measured angular autocorrelation functions, $w(\theta)$, for our photometric redshift bins $0.45 < z_{\text{phot}} < 0.5$ (top left-hand panel), $0.5 < z_{\text{phot}} < 0.55$ (top right-hand panel), $0.55 < z_{\text{phot}} < 0.6$ (bottom left-hand panel) and $0.6 < z_{\text{phot}} < 0.65$ (bottom right-hand panel), when no corrections are applied (black triangles), when corrections for stars and sky background are applied in the manner described by Section 3.3 (red squares; $C_{\text{star,sky}}$), when the effective area of stars, $A_{\text{star}}$, is removed from each pixel and a correction for sky background is applied (blue circles, $-A_{\text{star}}, C_{\text{sky}}$), when iterative weights are applied to the LG density field used to calculate $w(\theta)$ (green open triangles), and when $-A_{\text{star}}, C_{\text{sky}}$ is applied to the $w(\theta)$ of LGs selected such that $d_\perp > 0.5564$ and $0.0034$ is subtracted from $z_{\text{phot}}$ for objects in the South (orange open squares; $\Delta \text{South}$).

Figure 14. The measured angular autocorrelation functions, $w(\theta)$, for our photometric redshift bins $0.45 < z_{\text{phot}} < 0.5$ (top left-hand panel), $0.5 < z_{\text{phot}} < 0.55$ (top right-hand panel), $0.55 < z_{\text{phot}} < 0.6$ (bottom left-hand panel) and $0.6 < z_{\text{phot}} < 0.65$ (bottom right-hand panel), when no corrections are applied (black triangles), when corrections for stars and sky background are applied in the manner described by Section 3.3 (red squares; $C_{\text{star,sky}}$), when the effective area of stars, $A_{\text{star}}$, is removed from each pixel and a correction for sky background is applied (blue circles, $-A_{\text{star}}, C_{\text{sky}}$), when iterative weights are applied to the LG density field used to calculate $w(\theta)$ (green open triangles), and when $-A_{\text{star}}, C_{\text{sky}}$ is applied to the $w(\theta)$ of LGs selected such that $d_\perp > 0.5564$ and $0.0034$ is subtracted from $z_{\text{phot}}$ for objects in the South (orange open squares; $\Delta \text{South}$).

In order to subtract the effective area per star, $A_{\text{star}}$, for every star in each pixel, we use a different value of $r_{\text{star}}$ in each photometric redshift bin. We determine these values by fitting for the value of $r_{\text{star}}$ that makes $\bar{n}/\bar{n}(R_{\text{star}})$ most consistent with one for the objects in the redshift bin (just as was done for the full sample as described in Section 4.1). Further, we should expect slightly different values of $r_{\text{star}}$, given that Fig. 3 shows different relationships for different magnitude LGs, and the average magnitudes are different in each photometric redshift bin.

The $A_{\text{star}}, C_{\text{sky}}$ (blue circles) and $C_{\text{star,sky}}$ (red squares) corrections result in nearly identical measurements. Thus, the best-fitting bias values (as presented in Table 3) differ by no more than 1.5 per cent. Interestingly, the jack-knife errors are smaller in general when we subtract $A_{\text{star}}$, suggesting that this action reduces the fluctuations within the sample.

When we use the Weights method (open green triangles) to correct our measurements, the resulting $w(\theta)$ amplitudes are slightly smaller than any of the other measurements. This translates to
marginally lower (between 1.0 and 2.5 per cent compared to the ‘Corr’ values) best-fitting bias values. This suggests that the weights method may slightly suppress some true fluctuations. The jack-knife errors in the Weights case are similar to those determined using the $A_{\text{star}}$, $C_{\text{sky}}$ correction – applying the weights to the density field decreases the sample variance. The consistency between the best-fitting models and the data are also quite similar to the $A_{\text{star}}$, $C_{\text{sky}}$ results, except for bin 4, where $\chi^2$/d.o.f. decreases significantly.

Imposing the $d_L > 0.5564$ cut and subtracting 0.0034 from $z_{\text{phot}}$ for objects in the South and applying the $A_{\text{star}}$, $C_{\text{sky}}$ correction ($\Delta$South; orange open squares) only makes a significant difference in bin 4. The best-fitting bias values decrease by less than 1 per cent compared to the $A_{\text{star}}$, $C_{\text{sky}}$ best-fitting values for every bin other than bin 4, where find a 2.4 per cent decrease. Again compared to the $A_{\text{star}}$, $C_{\text{sky}}$ results, we find a marginal decrease in the $\chi^2$/d.o.f. values for bins 1 and 3, but for bin 2, we find a marginal increase. The increase in $\chi^2$/d.o.f. for bin 2 is driven mainly by the $w(\theta)$ measurement at 1/8. For bin 4, $\chi^2$/d.o.f. decreases by more than 50 per cent, and as can be seen in the bottom right-hand panel of Fig. 14, nearly all of the measurements at scales >3° become more consistent with the model.

In all of the bins, applying some form of correction reduces the $\chi^2$/d.o.f. values, and for bins 2-4, the corrections change the reduced $\chi^2$ by at least 1.8 (and by as much as 5.4 for bin 4). Further, the general agreement between the different methods of correction suggests that they can all be applied to recover measurements that more closely represent the true clustering of LGs. However, we note that they do not recover the exact same results, suggesting there is some level of systematic error that must be accounted for when similar measurements are used to constrain cosmological parameters. For bins 2 and 3, the variation in the best-fitting bias values is similar to the 1σ errors, suggesting the systematic uncertainties introduced by the need for corrections are approximately as large as the statistical uncertainties.

Considering all the results, we find the bias of the LGs is nearly constant as a function of redshift, with slight evidence of a decrease from high to low redshift. This is close to what we expect for a sample selected to be approximately passively evolving. Such a sample of $b \sim 2$ galaxies will undergo an ~4 per cent decrease in bias over the redshift range 0.475 < $z$ < 0.625 (see e.g. Fry 1996; Tegmark & Peebles 1998). More importantly, without any corrections, one might assume our model of large-scale clustering is grossly in error. However, with the corrections, we are given no reason to doubt the standard cosmological model. This is consistent with the results of Crocce et al. (2011b), whose $w(\theta)$ measurements, at similar redshifts to our own, are consistent with a $\Lambda$CDM model for scales $\theta < 5^\circ$.

Fig. 15 displays the fractional differences we find between the jack-knife errors and the theoretical errors we calculate, $\sigma_{\text{th}}$, divided by $\sigma_{\text{jack}}$ for the four photometric redshift bins 0.45 < $z_{\text{phot}}$ < 0.5 (black triangles), 0.5 < $z_{\text{phot}}$ < 0.55 (red squares), 0.55 < $z_{\text{phot}}$ < 0.6 (blue circles) and 0.6 < $z_{\text{phot}}$ < 0.65 (open green triangles). The solid lines connect the points representing the jack-knife errors and covariance matrix when no corrections are made, and the dashed lines connect the points representing the case where $A_{\text{star}}$ is subtracted for each star within a pixel of circular area corresponding to the radius $r_{\text{star}}$. The results are noisy, but the jack-knife and theoretical errors are similar at scales <10°, while the theoretical errors are larger at greater scales. We note that the agreement is due, in part, to the large differences in the best-fitting bias between the cases where corrections are and are not applied. The jack-knife errors are larger when no corrections are applied to the density field, but the best-fitting bias is larger as well (see Table 3), and thus the amplitudes of the jack-knife and theoretical errors are similar in both cases. In most cases, the jack-knife errors are smaller than the theoretical
estimate at large scales, but this effect is more dramatic when corrections are applied to the density field. One would expect that the jack-knife errors should underestimate the true uncertainty as the scale grows larger and the different jack-knife regions thus become more correlated.

Fig. 16 presents the angular cross-correlation functions between our four photometric redshift samples, after applying corrections for stars and sky background. For comparison, we display model curves where we assume a bias equal to the geometric mean of the bias of the two bins being cross-correlated (i.e. for $2 \times 3, b = 2.06$). In general, the amplitudes of the cross-correlations are consistent with the redshift distributions determined from our testing set. The cross-correlations that are least consistent are $1 \times 2$ and $2 \times 3$. The inconsistency could be due to a number of factors. Apart from the redshift distributions being incorrect, it is possible that the bias of the galaxies contributing to the cross-correlation (e.g. for $2 \times 3$, the high-redshift edge of the $0.5 < z_{\text{phot}} < 0.55$ distribution) is lower than for the overall sample. This is likely if objects with lower bias also have larger photometric redshift errors. The facts that the model curves for $1 \times 2$ and $2 \times 3$ are only marginally outside the $1\sigma$ errors and that the agreement appears excellent for the other cross-correlations suggest that there is no significant disagreement. If we do not apply the corrections to the measurements, they are greatly divergent from the models.

6.2 Comparison with the MegaZ-LRG DR7 catalogue

The MegaZ-LRG DR7 catalogue (hereinafter MegaZ) is a photometric redshift catalogue similar to our own (Thomas et al. 2011a). It used ANNz to train SDSS DR7 objects with similar colour selection to ours and spectroscopic redshifts from the 2SLAQ survey (Cannon et al. 2006). Compared to the sample used in Thomas et al. (2011a), the most notable differences are that they impose a cut $i_{\text{abv}} < 19.8$, while the BOSS uses $i_{\text{cmd}} < 19.9$ and the sliding cut defined by equation (6). Further, 2SLAQ spectra were targeted for objects with $i_{\text{abv}} < 21.4$, where $i_{\text{abv}}$ is the $i$-band magnitude within a 3-arcsec aperture (our fibre-magnitude cut is $i_{\text{fib}} < 21.7$).

The MegaZ data and its corresponding mask are publicly available. Similar to our catalogue, there is a photometric redshift and a probability that the object is a galaxy (we denote this by $p_{\text{gal}}$). We employ the same cuts on the MegaZ catalogue as Thomas et al. (2011a), the most notable one being $p_{\text{gal}} > 0.2$. Different target selections result in discrepancies between the overall redshift distributions. These disagreements are most extreme for the lowest and highest redshift bins. Weighting by $p_{\text{gal}}$, our catalogue has 20 per cent of its objects with $0.45 < z_{\text{phot}} < 0.5$, while the MegaZ catalogue has 36 per cent of its data in this redshift bin. The $0.6 < z_{\text{phot}} < 0.65$ photometric redshift bin contains 14 per cent of our data, while only 10 per cent of the MegaZ data have photometric redshifts in this range. Our overall number density is slightly smaller; however, as for $0.45 < z_{\text{phot}} < 0.65$, we have a number density of 88 deg$^{-2}$ (872 921 objects over 9913 deg$^2$) and MegaZ has a number density of 93 deg$^{-2}$ (723 556 objects over 7746 deg$^2$).

The mask provided by MegaZ is in the HEALPix format at $N_{\text{side}} = 1024$, and we can therefore calculate $w(\theta)$ using nearly-identical methods as described in Section 3.1. We calculate $w(\theta)$ for MegaZ data in the same four photometric redshift bins as our own catalogue (we note these are also the photometric redshift bins used by Thomas et al. 2011a). We display these measurements, compared to our own, in Fig. 17. The black triangles display the measurements we obtain when we cut objects from the MegaZ catalogue with $p_{\text{gal}} < 0.2$, while the red squares display the results when we correct the same MegaZ measurements for stars in the DR7 area, using the Corr technique described in Section 3.3. The blue circles display the measurements of $w(\theta)$ for the full DR8 area, when the Corr technique is applied for stars.

The small-scale amplitudes of the MegaZ measurements and our own are not directly comparable, because the redshift distributions

12 http://zuserver2.star.ucl.ac.uk/~sat/MegaZ/MegaZDR7.tar.gz
Ameliorating systematic uncertainties in $w(\theta)$ may be different. However, Thomas et al. (2011a) find a significantly smaller bias in their $0.45 < z_{\text{phot}} < 0.5$ bin than their other bins, whereas we find only a small difference in the bias of our different photometric redshift bins (see Table 1). It therefore makes sense that the MegaZ amplitudes are significantly smaller than ours. For the middle two redshift bins, the small-scale amplitudes of the MegaZ measurements and our own are generally consistent with the displayed jack-knife errors. This result is no surprise, given that we would expect the (small) differences in the target selection to only significantly affect the highest and lowest portions of the redshift distribution. Finally, Thomas et al. (2011a) found a substantially higher bias in the MegaZ $0.6 < z_{\text{phot}} < 0.65$ sample than in their other bins, while for our sample, the bias in this bin is quite similar to that of the $0.55 < z_{\text{phot}} < 0.6$ bin. Therefore, the MegaZ amplitudes are larger than ours for $0.6 < z_{\text{phot}} < 0.65$.

Correcting for stars makes a substantial difference in the large-scale clustering of the MegaZ data in the lowest and highest redshift bins, but has little effect in the middle two bins. We note that our measurements show no appreciable change when we use only the DR7 area, suggesting that the differences between the two samples must be due to additional systematic effects on either the MegaZ data or our own.

We note that Thomas et al. (2011a) measured $C_\ell$ with these MegaZ samples and found significant deviations in the expected clustering (from $\Lambda$CDM models) to be confined to the lowest $\ell$ bins. For measurements of $w(\theta)$, the covariance between angular scales implies that an excess at low $\ell$ will affect measurements at smaller angular scales. Given that

$$w(\theta) = \sum_{\ell \geq 0} \left( \frac{2\ell + 1}{4\pi} \right) P_\ell(\cos \theta) C_\ell,$$

where $P_\ell$ are Legendre polynomials, one can determine that a 400 per cent excess for $\ell < 5$ and a 50 per cent excess for $5 < \ell < 10$ (similar to the excess found in the $0.6 < z_{\text{phot}} < 0.65$ bin by Thomas et al. 2011b) translate to a 30 per cent larger $w(\theta)$ at $\theta = 3^\circ$. This estimate is roughly consistent with the difference between the uncorrected (black triangles) and corrected (red squares) MegaZ $w(\theta)$, displayed in the lower right-hand panel of Fig. 17, that is, we find the systematic effect of stars of the $0.6 < z_{\text{phot}} < 0.65$ MegaZ $w(\theta)$ to be consistent with the low $\ell$ excess found by Thomas et al. (2011b).

Failure to apply correction for the systematic effects described in this paper would clearly bias the cosmological parameters one could determine based on our $w(\theta)$ measurements. However, our results suggest that $C_\ell$ measurements for $\ell > 10$ might not result in biased measurements. We therefore have no reason to believe that the measurements of cosmological parameters by Thomas et al. (2011a) have significant systematic errors associated with them. The magnitude of potential systematic errors on the cosmological parameters determined with $C_\ell$ spectra is studied in detail in Ho et al. (in preparation).

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Figure 17. The measured angular autocorrelation functions in the four photometric redshift bins $0.45 < z_{\text{phot}} < 0.5$ (top left-hand panel), $0.5 < z_{\text{phot}} < 0.55$ (top right-hand panel), $0.55 < z_{\text{phot}} < 0.6$ (bottom left-hand panel) and $0.6 < z_{\text{phot}} < 0.65$ (bottom right-hand panel). The black triangles display the results using the same catalogue (and cuts on it) as Thomas et al. (2011b). The red squares show the MegaZ measurements when they are corrected for stars and the blue circles are the measured $w(\theta)$ using our catalogue and correcting for stars, as described in Section 3.3.
7 CONCLUSIONS

We have investigated the systematic effects on the angular distribution and spectroscopic/photometric redshift distributions of objects matching the BOSS CMASS selection. We find that not correcting for the foreground presence of stars, which effectively mask small areas of the sky, produces a systematic error that is (generally) significantly larger than the statistical error at scales greater than 3°. The measured $w(\theta)$, after accounting for foreground stars, are generally consistent with $\Lambda$CDM predictions, even at the largest scales we measure, but are grossly inconsistent ($\chi^2$/d.o.f. as large as 6.3) when the effects of foreground stars are ignored. Our primary results can be summarized as follows:

(i) We select objects from the SDSS DR8 CAS, using the criteria defined for the BOSS CMASS sample, yielding a sample of 1065823 objects within our masked footprint which are matched to 112778 existing BOSS spectra (see Section 2.1). We train ANN$z$ to output a probability that each of these objects is a galaxy (see Section 2.2).

(ii) Stars occult a small area of the sky, reducing the ability to detect galaxies in their immediate vicinity (see Fig. 3). For our sample, stars with $i$-band magnitude less than 20.3 have an effect out to at least 10 arcsec (see the top right-hand panel of Fig. 3).

(iii) We account for stellar contamination by weighting every object by the probability that it is a galaxy. When doing so, we find a strong, negative correlation between the number density (in $\text{deg}^{-2}$) of objects in our sample and stars (see the red squares in the bottom left-hand panel of Fig. 4 and the black triangles in the bottom panel of Fig. 5), partially explained by our finding that stars effectively mask their local area.

(iv) We correct for the effect of stars on the local density of galaxies by assuming each star effectively removes constant amount of area. We determine this area as described in Section 4.1. We find that accounting for this area produces a significant change in $w(\theta)$, especially at large scales (see the left-hand panel of Fig. 7).

(v) We test two methods that can be applied in an attempt to correct for the systematic errors introduced by any parameter that can be turned into a map on the sky. The ‘Corr’ technique, first developed for large-scale structure measurements by Ho et al. (in preparation), is described in Section 3.3. When this method is applied to correct for the presence of stars, we recover nearly identical results as when we account for the effective area of stars (see the left-hand panel of Fig. 7). The ‘Weights’ method is described in Section 4.3. We find that applying it to stars, Galactic extinction, seeing, sky background, airmass and Schlafly et al. (2010) offsets in $d_\perp$ results in $w(\theta)$ measurements that are nearly identical to those we obtain applying the Corr method to stars and sky background (see the right-hand panel of Fig. 7).

(vi) We use ANN$z$ to estimate photometric redshifts for every object in our sample. We find that including axial ratios improves the accuracy of the photometric redshift estimates in our testing set (see Section 5.1), and that including Galactic extinction improves their reliability when applied to the full sample (see Section 5.2).

(vii) We find an asymmetry in the density of objects in the North and South Galactic caps, which is removed (to within 0.1 per cent) when we account for the 0.0064 difference in $d_\perp$ between the North and South, discovered by Schlafly & Finkbeiner (2010) (see Section 4.4). This offset in $d_\perp$ implies that the photometric redshift estimates in the South are biased by 0.0034 compared to the North.

When we correct for this bias, we find that the ratio of the number of galaxies in the South to the number in the North is approximately constant and consistent with the ratio of their areas for $0.46 < z_{\text{phot}} < 0.65$ (see Fig. 12). Our $w(\theta)$ measurements for the full sample appear similar to a weighted average of $w(\theta)$ calculated separately for the North and South (see Fig. 8).

(viii) We divide our photometric redshift catalogue into four photometric redshift slices between $0.45 < z_{\text{phot}} < 0.65$, as summarized in Table 2. We measure $w(\theta)$ for each slice, applying the various techniques we developed to correct for systematic errors (see Fig. 15). We calculate the bias in each sample when using each of the techniques, assuming the same fiducial $\Lambda$CDM model, the results of which are summarized in Table 3.

(ix) We find that the magnitude of the corrections is larger than the statistical error for $z_{\text{phot}} > 0.5$ and $\theta > 3^\circ$ and that applying some form of correction significantly reduces the minimum $\chi^2$/d.o.f.

(x) We find scatter in the best-fitting bias values that is similar to their 1σ uncertainty, suggesting that the systematic error introduced by the need for corrections is of similar magnitude to the statistical uncertainty.

The presence of foreground stars must be accounted for in any study of large-scale clustering – including the three-dimensional clustering of the BOSS spectroscopic data. Further, similar tests to those presented here will likely be necessary for the radial distribution of BOSS LGs and its impact on the measured clustering.

The results of our study have strong implications for future photometric redshift surveys (such as DES, PanSTARRS and LSST). We are able to extensively investigate potential sources of systematics because we are determining $z_{\text{phot}}$ estimates in the most ideal of cases: our training sample covers a large area, is representative and 10 per cent as large as our full catalogue. Further, we can include Galactic extinction values in the training because the training sample covers a range representative of our full sample.

As documented throughout, it is not only the accuracy of the $z_{\text{phot}}$ estimate that is important, but also the probability that an object is a galaxy. Reliable probabilities that an object is a galaxy are crucial for disentangling the systematic and contamination effects of stars on the density field of LGs. Even though our training set is quite large, the relationship shown in Fig. 2 is fairly noisy, implying that identifying robust methods of assigning probabilities that objects are galaxies should be a major focus of forthcoming photometric redshift surveys.

Our ideal conditions may not be replicated often in the future (though the photometry should be much better) and many photometric redshifts will be determined via extrapolation of spectral templates. Robust and exhaustive exploration of potential systematics will be difficult under such circumstances, yet extremely important, and their errors are likely to dominate at large scales. It is encouraging that Thomas et al. (2011a) find very similar best-fitting cosmological values when they separately use ANN$z$ and various template-based methods to determine their photometric redshifts.

Finally, the results we present suggest that the major systematic effects on our photometric redshift catalogue of LGs have been identified and can be corrected for, allowing for robust cosmological measurements. Ho et al. (in preparation) show how the same systematics can be accounted for using the angular power spectrum and present the cosmological constraints obtained using the catalogue of galaxies whose creation is described in this paper.

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APPENDIX A: STELLAR CONTAMINATION

Studies such as Myers et al. (2006) have previously described methods for identifying and correcting for stellar contamination. However, Fig. 3 and the left-hand panel of Fig. 4 show that the effect of stars on the density field of LGs is two-fold: (1) some of the objects are stars and these are thus contaminants; and (2) the presence of stars systematically affects the number density of objects. Accounting for both effects makes equations (28)–(30) more complicated. Given some fraction of the objects that are galaxies, $f_g$, and some fraction that are stars, $f_s$, they become

$$\delta_g^\prime = f_g (\delta_g + \epsilon \delta_s) + f_s \delta_s,$$  \hspace{1cm} (A1)

$$w_g^\prime(\theta) = w_g(\theta)/f_g^2 - w_1(\theta)\epsilon^2 - w_{\text{sc}}(\theta)(f_s/f_g)^2 - w_{\text{sc}}(\theta)\epsilon f_s/f_g,$$ \hspace{1cm} (A2)

and

$$\epsilon = \frac{w_g^\prime(\theta) - f_s w_{\text{sc}}(\theta)}{f_s w_{\text{sc}}(\theta)},$$ \hspace{1cm} (A3)

where $\delta_s$ is the overdensity of stars that act as contaminants and $\delta_i$ is the overdensity of all stars. The sum of $p_{sc}$ for the full catalogue suggests that 95.9 per cent of the objects in the catalogue are galaxies. Our training data imply that $\sim 1.2$ per cent of these objects are quasars.

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We therefore assume \( f_g = 0.96 \) and \( f_s = 0.03 \). We measure \( w(\theta) \) and the cross-correlation between LGs and stars using our full catalogue, equally weighting each object. If we assume that \( \delta_i = \delta_{sg} \) and determine \( \epsilon \) via equation (A3), we find the result plotted in the black triangles in the bottom panel of Fig. A1. The result is extremely close to the value of \( \epsilon \) we obtain when we weight by \( p_{sg} \), which is plotted with a solid black line.

The top panel of Fig. A1 displays the \( w(\theta) \) measured without any corrections or \( p_{sg} \) weights (black triangles). The red squares display the result when we correct for the contamination and systematic effects of stars. This yields similar results as when we correct the \( p_{sg} \)-weighted measurements for the systematic effect of stars (solid line), but the unweighted correction is systematically smaller than what would be required for the unweighted and weighted results to agree. The disagreement is likely due to the fact that we are assuming \( \delta_i = \delta_{sg} \) and that we know \( f_g \). While we can be confident in the value of \( f_g \) by summing \( p_{sg} \), the fact that some of the objects are quasars implies we do not have an estimate of \( f_s \). Further, it is quite possible that the stars that are mistaken for LGs and are in our sample have a different distribution than the full distribution of stars. Thus, we are making a number of (possibly incorrect) assumptions.

The approach we adopt in this paper is to weight each LG by its value of \( p_{sg} \). Assuming that the \( p_{sg} \) values are accurate, this weighting effectively makes \( f_g = 1 \) (and \( f_s = 0 \)), considerably simplifying the situation. We no longer have to worry about the percentage of objects that are quasars or if the distribution of contaminant stars is different from the full distribution of stars. When there is stellar contamination, the cross-correlation between the observed LG density field and that of the stars will be \( \sim f_g \epsilon w_s(\theta) + f_s w_s(\theta) \). The autocorrelation function of stars is positive and their cross-correlation function with LGs is negative (implying \( \epsilon \) is negative). Therefore, when there is stellar contamination, one is likely to measure a cross-correlation that is \( \sim 0 \). This would make one (incorrectly) assume that stars have no effect on the measured autocorrelation function of the LGs. Note that a cross-correlation of \( \sim 0 \), when one knows that stellar contamination exists, implies that there must be a systematic effect of the stars on the density field (since the autocorrelation function of the stars is non-zero). We strongly recommend that, given reliable probabilities, one weights an object by the probability that it is a galaxy when measuring autocorrelation functions.

**APPENDIX B: SYSTEMATIC CORRECTIONS**

We display the solutions for \( \epsilon_i \) based on equations (29) and (30) (as first derived by Ho et al., in preparation) for up to three systematics:

\[
\epsilon_3 = \frac{w_{g,3} \left( w_{2} w_{1}^2 - w_{1} w_{1,1} - w_{1,1,3} - w_{1} w_{1,1,2} + w_{1} w_{1,1,2} - w_{1} w_{1,1,2} - w_{1} w_{1,1,2} + w_{1} w_{1,1,2} - w_{1} w_{1,1,2} \right)}{w_{1} w_{1}^2 - w_{1} w_{1,1} - w_{1} w_{1,1} - w_{1} w_{1,1} - w_{1} w_{1,1} - w_{1} w_{1,1} - w_{1} w_{1,1} - w_{1} w_{1,1}} \tag{B1}
\]

\[
\epsilon_2 = \frac{w_{1} w_{1} - w_{1} w_{1,1}}{w_{1} w_{1}^2 - w_{1} w_{1,1}} \left( w_{g,2} - \frac{w_{1,2}}{w_{1}} (w_{g,1} - \epsilon_1 w_{2,3}) - \epsilon_2 w_{2,3} \right) \tag{B2}
\]

\[
\epsilon_1 = \frac{1}{w_{1}} \left( w_{g,1} - \epsilon_2 w_{1,2} \right) \tag{B3}
\]

where \( w_{i,j} \) is the cross-correlation function of the galaxies and potential systematic \( i \) and \( w_{i,j} \) is the cross-correlation function of systematics \( i \) and \( j \) (and is an autocorrelation function when \( i = j \)). For only one systematic, the result is simple; one simply subtracts \( \epsilon^2 w_{sys}(\theta) \) from the measured LG \( w(\theta) \).
We note that the solutions we present are implicitly dependent on $\theta$, but $\epsilon$, as defined, is a constant [equation (28) does not allow for a $\theta$ dependence]. If the measured value of $\epsilon$ changes depending on $\theta$, higher order corrections may be necessary. In this work, we did not find that the error bars on $\epsilon$ (as displayed in Fig. 6) warranted applying higher order corrections. However, the value of $\epsilon$ for the seeing does appear to have a strong dependence on the angular scale, suggesting that if the errors were smaller, higher order corrections could become necessary.